

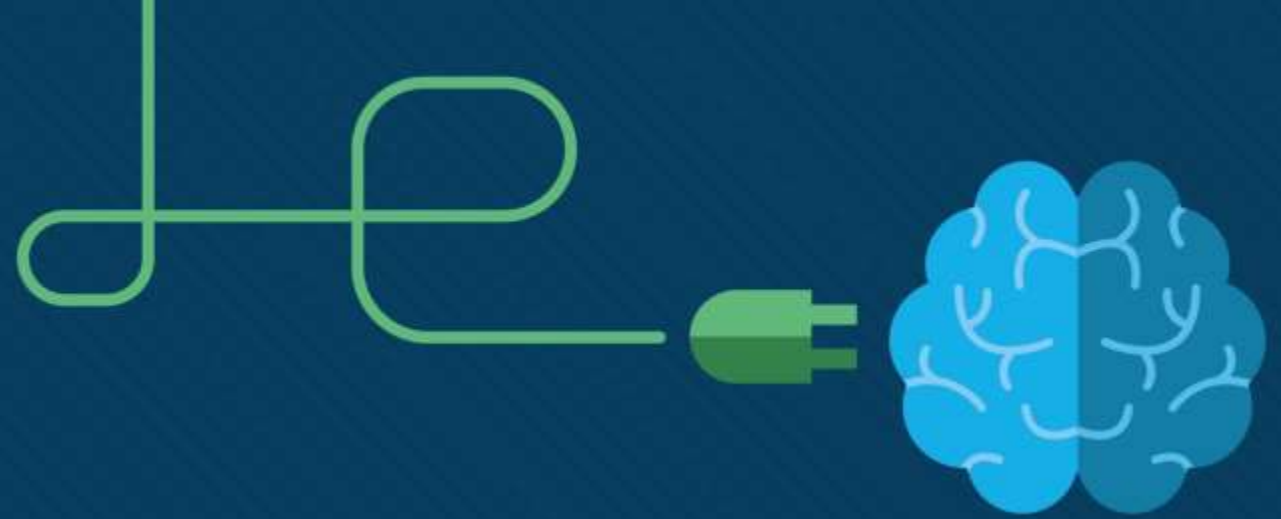


Python Institute

15:35 a 16:45h

Una introducción práctica al procesamiento de imágenes y la visión artificial con Python

Jordi Ariño | Software Developer Manager at PUE



PCAP

Programming Essentials in Python

Una introducción práctica al procesamiento de imágenes y la visión artificial con Python





Jordi Ariño

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Agile Software Developer

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[@jordiAS2K](https://twitter.com/jordiAS2K)



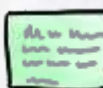

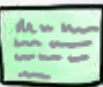



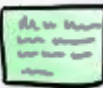

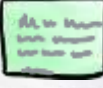

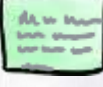

#PUEAcademyDay19



Introducción





	To do	Doing	Done
			
			
			
			
			
			

Agenda

- 1.- Introducción
- 2.- Python en la actualidad
- 3.- CNA: Portfolio educativo
- 4.- PCAP: Programming Essentials in Python
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Este **workshop** se enmarca dentro de la iniciativa de colaboración entre **Python Institute** y el programa **Cisco Networking Academy**.

Esta colaboración nace con el objetivo de ofrecer una serie de **recursos docentes**, a disposición de los centros Cisco Academy y sus instructores, para la formación de sus alumnos en **Python**.


Entre estos recursos docentes ofrecidos destaca el curso **PCAP: Programming Essentials in Python** disponible dentro de la plataforma *NetAcad*.



Objetivo: Analizar el contenido y formato del curso **PCAP** y ver cómo permite formar a los alumnos en las habilidades necesarias para iniciarse en la programación con Python.

Este curso permite obtener un conjunto de conocimientos fundamentales y habilidades de programación necesarias en los campos de uso de Python: IA, Data Science, Machine Learning, visión por computador, IoT, estadística, ...

Como **caso práctico** realizaremos una sencilla introducción de cómo utilizar Python en el campo del procesamiento de imágenes y vídeos dentro de la **visión por computador** o **visión artificial**.



PYTHON INSTITUTE
Open Education & Development Group

Networking Academy
CISCO

Programación
PCAP: Programming Essentials in Python
Por Cisco Networking Academy, en colaboración con
OpenEDG Python Institute

Python Institute

Python Institute es un proyecto independiente sin ánimo de lucro desarrollado por el Open Education and Development Group (**OpenEDG**).

Nace con el principal objetivo de promover el lenguaje de programación Python, y ayudar en la formación de una nueva generación de programadores.

Ha desarrollado, en colaboración con Pearson VUE, un **programa de certificación** independiente y *vendor-neutral* en el lenguaje de programación Python.

Iniciativa de colaboración entre **Python Institute** y el programa **Cisco Networking Academy**.



LEARN, CERTIFY, PROGRAM YOUR CAREER



LEARN PYTHON

Sign up for PCAP | Programming Essentials in Python to dive into programming and learn Python from scratch!



BECOME CERTIFIED

Python certification will help you stand out. Become Python Certified and make the change!



BOOST YOUR CAREER

Certification opens doors to a better job and a better salary. Take your career to the next level!



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con
OpenEDG Python Institute

Certificación PCAP

Nombre: Certified Associate in Python Programming

Código: PCAP-31-02

Versión: Python 3.x

Nivel: Associate

Pre-requisitos: Ninguno

Duración: 65 min

Preguntas: 40 preguntas

Formato: Tipo test (*single/multiple choice*)

Passing Score: 70% (28/40)

Idioma: Inglés



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con
OpenEDG Python Institute

Certificación PCAP

Exam block #1

Control and Evaluations (25%)

Exam block #2

Data Aggregates (25%)

Exam block #3

Functions and Modules (25%)

Exam block #4

Classes, Objects and Exceptions (25%)



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con OpenEDG Python Institute

What snippet would you insert in the line indicated below:

```
n = 0
```

```
while n < 4:
```

```
    n += 1
```

```
    # insert your code here
```

To print the following string to the monitor after the loop finishes its execution:

```
1 2 3 4
```

- A. `print(n)`
- B. `print(n, sep=" ")`
- C. `print(n, end=" ")`
- D. `print(n, " ")`

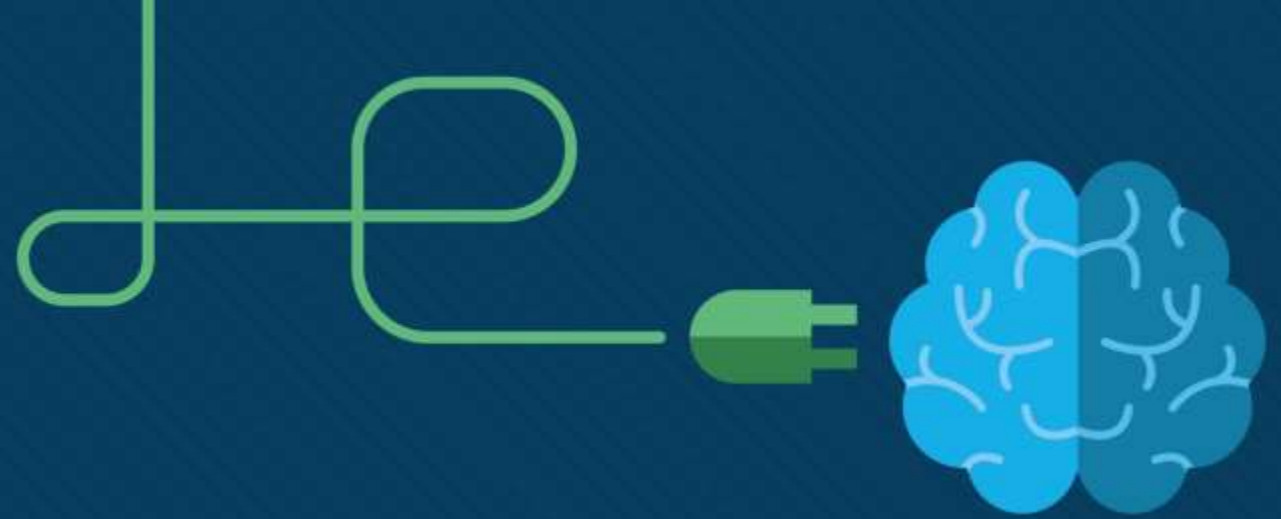


Con la inscripción a este workshop habréis recibido acceso, como alumno, al curso **PCAP: Programming Essentials in Python** dentro de la plataforma NetAcad de Cisco.

Objetivo: Poder evaluar el curso y los recursos e-learning que Cisco pone a disposición de centros y profesores para la formación de sus alumnos en programación en Python de forma práctica, oficial y reconocida.

Destacar, como valor añadido, que este curso ayuda a los estudiantes en su preparación para la certificación oficial:

- **PCAP – Python Certified Associate Programmer**



Python en la actualidad





	To do	Doing	Done

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Python en la actualidad



A día de hoy, **Python es uno de los lenguajes de programación más populares y extendidos**, adoptado en la mayoría de sectores e industrias.

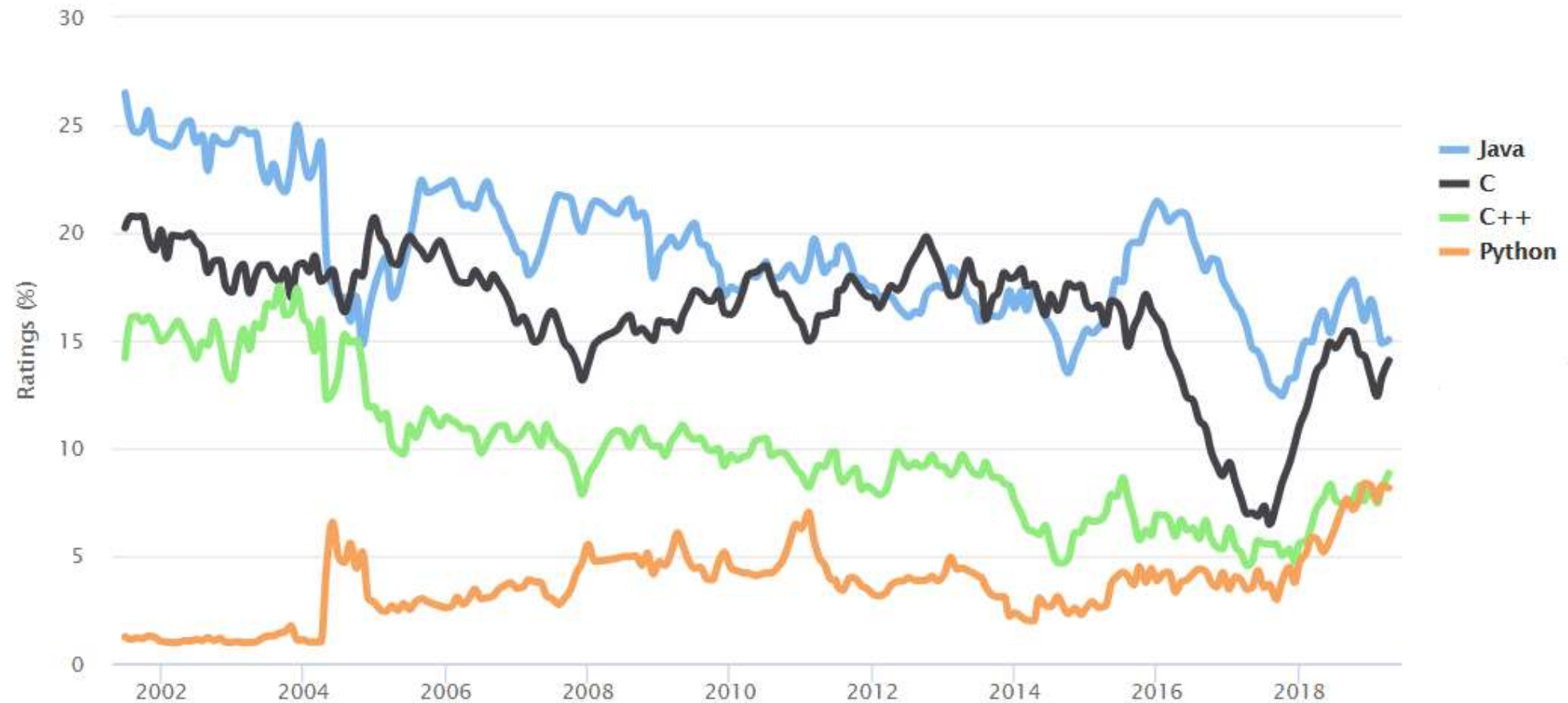
Ha sido nombrado el **lenguaje del año 2018** por el índice **TIOBE**.

El índice **PYPL** (PopularitY of Programming Language), considera a Python el **lenguaje más popular** y el que ha experimentado **un mayor crecimiento** en estos últimos 5 años (17.1%).

La tendencia del mercado laboral muestra que la demanda de profesionales de Python crece exponencialmente cada año.

Python en la actualidad

TIOBE Programming Community Index



TIOBE Programming Community Index

Apr 2019	Apr 2018	Change	Programming Language	Ratings	Change
1	1		Java	15.035%	-0.74%
2	2		C	14.076%	+0.49%
3	3		C++	8.838%	+1.62%
4	4		Python	8.166%	+2.36%
5	6	▲	Visual Basic .NET	5.795%	+0.85%
6	5	▼	C#	3.515%	-1.75%
7	8	▲	JavaScript	2.507%	-0.99%
8	9	▲	SQL	2.272%	-0.38%
9	7	▼	PHP	2.239%	-1.98%
10	14	▲▲	Assembly language	1.710%	+0.05%

Python en la actualidad

TIOBE Programming Community Index

Year	Winner
2018	🏆 Python
2017	🏆 C
2016	🏆 Go
2015	🏆 Java
2014	🏆 JavaScript
2013	🏆 Transact-SQL
2012	🏆 Objective-C
2011	🏆 Objective-C

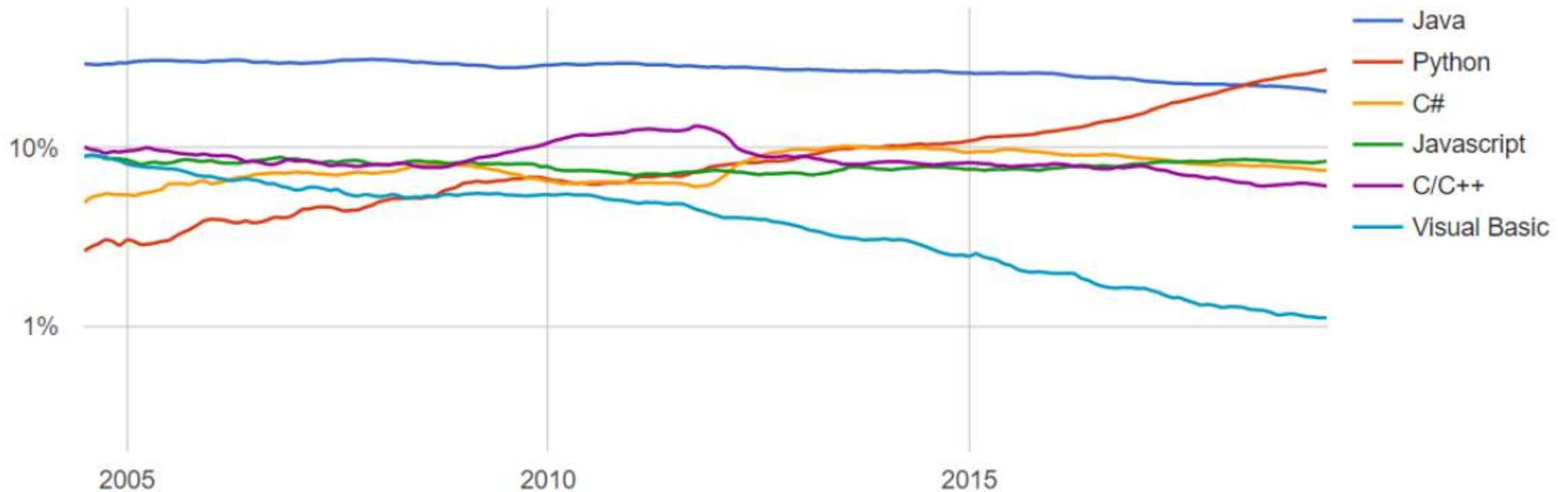
Python en la actualidad

TIOBE Programming Community Index

Programming Language	2019	2014	2009	2004	1999	1994	1989
Java	1	2	1	1	13	-	-
C	2	1	2	2	1	1	1
C++	3	4	3	3	2	2	2
Python	4	7	5	9	26	21	-
Visual Basic .NET	5	10	-	-	-	-	-
C#	6	5	6	7	23	-	-
JavaScript	7	8	8	8	18	-	-
PHP	8	6	4	5	-	-	-
SQL	9	-	-	6	-	-	-

Python en la actualidad

PYPL Popularity of Programming Language



Python en la actualidad

PYPL Popularity of Programming Language

Worldwide, Apr 2019 compared to a year ago:

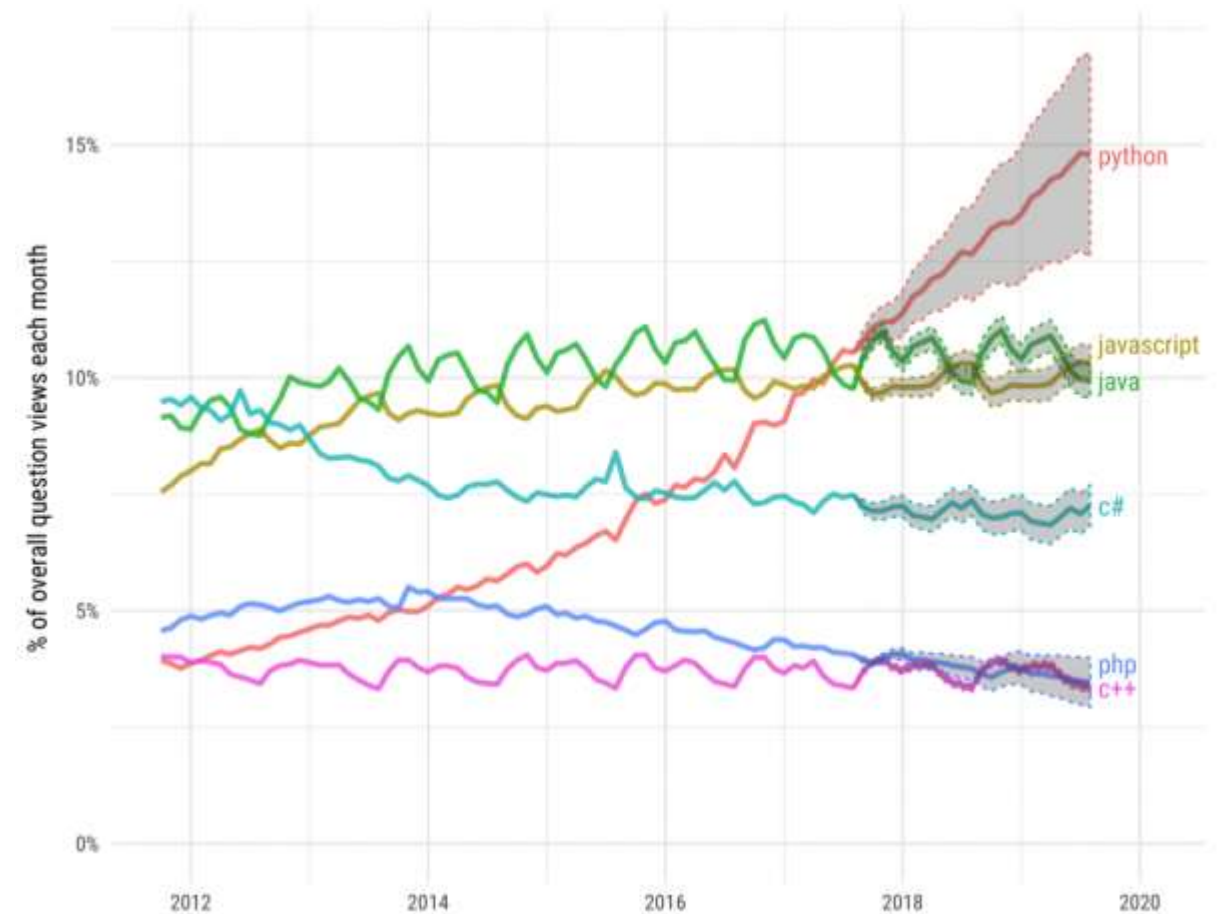
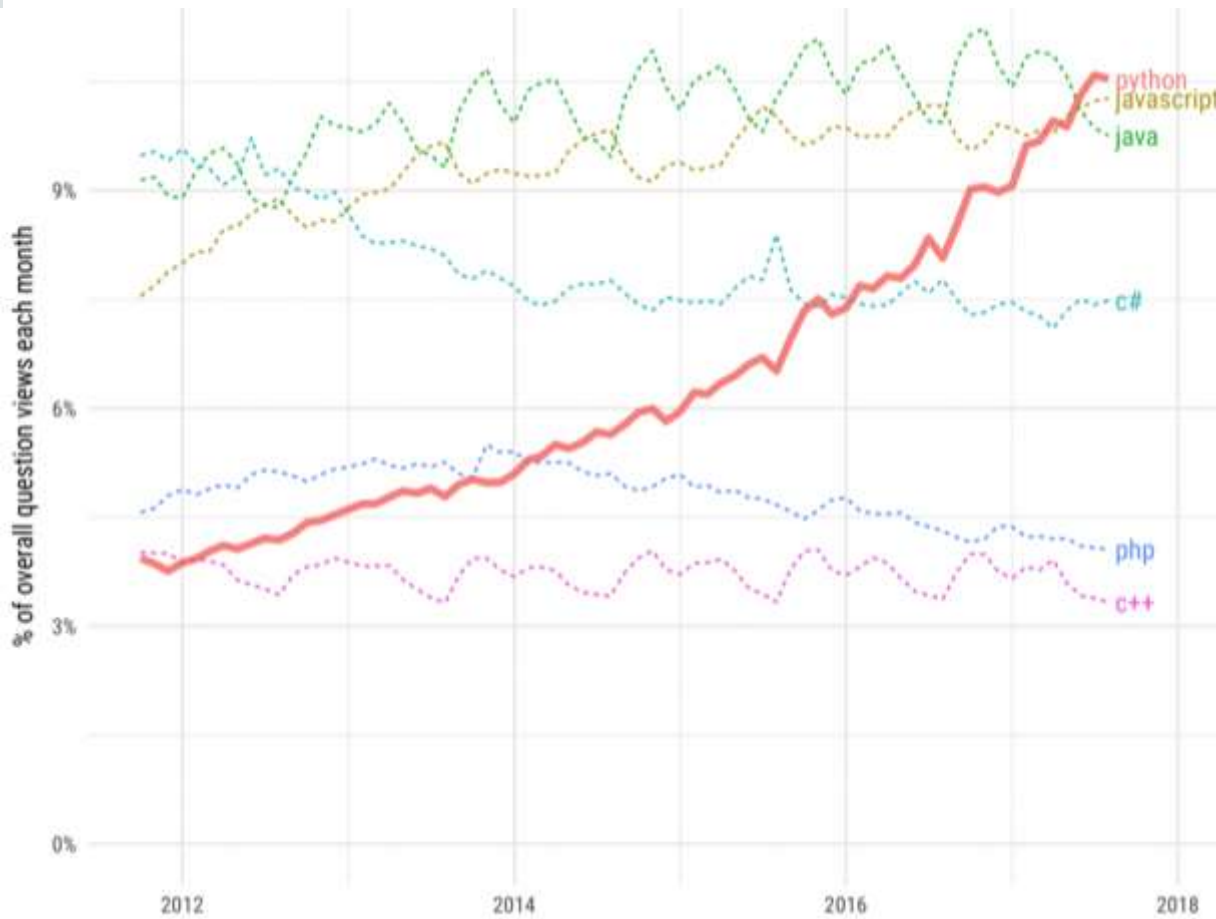
Rank	Change	Language	Share	Trend
1	↑	Python	27.35 %	+5.2 %
2	↓	Java	20.64 %	-1.8 %
3		Javascript	8.4 %	-0.2 %
4	↑	C#	7.45 %	-0.5 %
5	↓	PHP	7.18 %	-1.1 %
6		C/C++	6.08 %	-0.3 %
7		R	4.18 %	-0.1 %
8		Objective-C	2.86 %	-0.8 %
9		Swift	2.47 %	-0.4 %
10		Matlab	2.06 %	-0.3 %

Worldwide, Apr 2019 compared to a year ago:

Rank	Change	Language	Share	Trend
11	↑	TypeScript	1.64 %	+0.2 %
12	↓	Ruby	1.39 %	-0.3 %
13		VBA	1.39 %	+0.0 %
14	↑↑	Kotlin	1.18 %	+0.3 %
15		Scala	1.16 %	-0.0 %
16	↑	Go	1.14 %	+0.3 %
17	↓↓↓	Visual Basic	1.11 %	-0.2 %
18		Perl	0.58 %	-0.2 %
19		Rust	0.54 %	+0.2 %
20		Lua	0.37 %	+0.0 %

Python en la actualidad

Stack Overflow Trends





¿Qué hace que Python sea tan especial?

- Es **fácil de aprender**: el tiempo necesario para aprender Python es más corto que en muchos otros lenguajes.
- Es **fácil de enseñar**: la carga de trabajo de enseñanza es más pequeña que la que necesitan otros lenguajes.
- Es **fácil de entender**; a menudo, también es más fácil entender el código de otra persona más rápido si está escrito en Python.
- Es **fácil de obtener, instalar y desplegar**: Python es gratuito, abierto y multiplataforma.
- Ofrece un gran ecosistema de **paquetes, librerías y frameworks**



Find, install and publish Python packages with the Python Package Index



Or [browse projects](#)

177,638 projects

1,300,352 releases

1,863,365 files

324,283 users



The Python Package Index (PyPI) is a repository of software for the Python programming language.

PyPI helps you find and install software developed and shared by the Python community. [Learn about installing packages.](#)

Package authors use PyPI to distribute their software. [Learn how to package your Python code for PyPI.](#)

Trending projects

Trending projects as downloaded by the community



[guillotina-oauth 2.0.0](#)
guillotina oauth support

New releases

Hot off the press: the newest project releases



[sheet-disk 0.1.1](#)
Use Google Sheets as a storage device!

The Python Package Index (PyPI)

PyPI has over more than 160,000 packages. Here are some of its functionalities



Graphical User Interfaces



Scientific Computing



System Administration



Image Processing



Web Frameworks



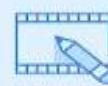
Test Frameworks



Documentation



Databases



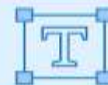
Multimedia



Networking



Automation



Text Processing

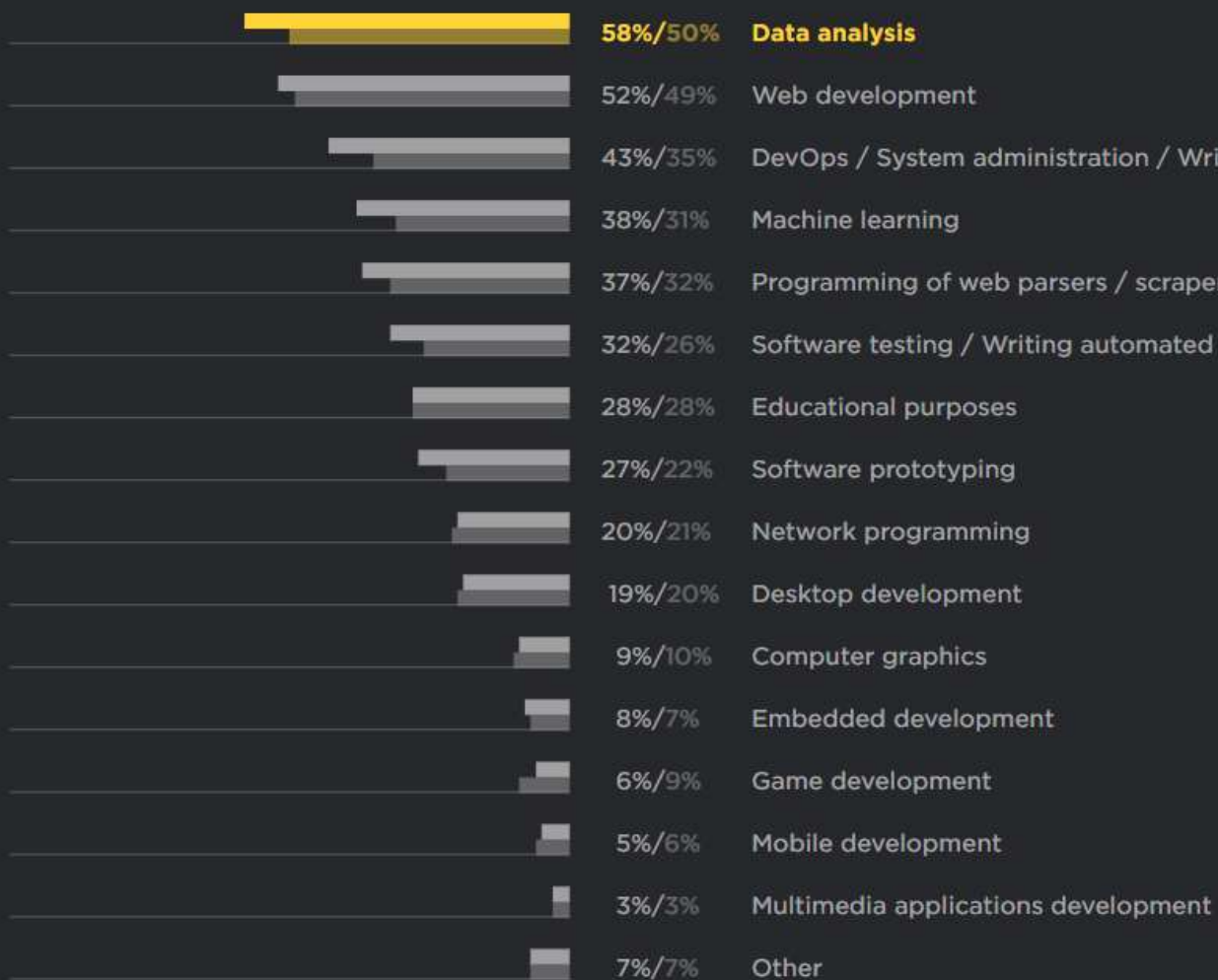
● 2018

● 2017

Combined

Python is main

Python is secondary



Python Developers Survey 2018

Interesting fact

In 2018 we had significantly more respondents specifying they're involved in DevOps (an increase of 8% compared to 2017). In terms of Python users using Python as their secondary language, DevOps has overtaken web development.

Worth noting is that Data analysis has become more popular than Web development, growing from 50% in 2017 to 58% in 2018. Machine learning also grew by 7 percentage points. These types of development are experiencing faster growth than Web development, which has only increased by 2 percentage points when compared to previous year.

16 Famous Companies that uses PYTHON

Quora



You Tube

Google

edX

YAHOO!



yelp.



Dropbox

IBM



DISQUS



Eventbrite





CNA: Porfolio educativo





	To do	Doing	Done

Agenda

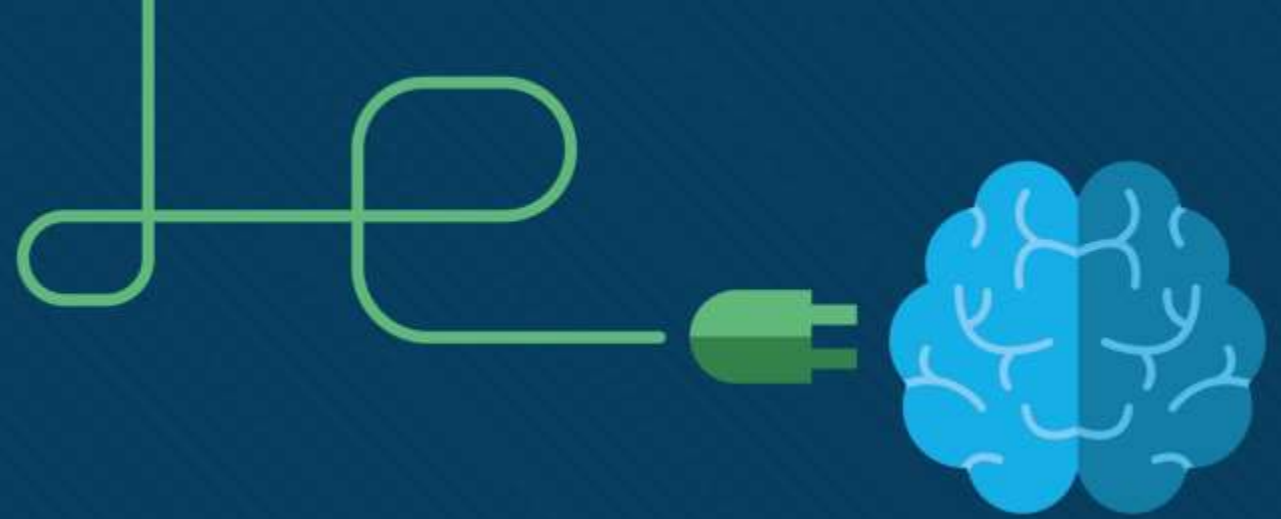
- 1.- Introducción
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El portafolio educativo de Networking Academy

		Colaborar para generar impacto				
		Introduction to Packet Tracer	Packet Tracer	Hackatones	Prototyping Lab	Prácticas laborales
		Exploratorio	Básico	Profesional		
Redes			<ul style="list-style-type: none"> Networking Essentials Mobility Fundamentals Talleres de tecnología emergente: Programabilidad de redes con Cisco APIC-EM* 		<ul style="list-style-type: none"> CCNA R&S: Introduction to Networks, R&S Essentials, Scaling Networks, Connecting Networks CCNP R&S: Switch, Route, Tshoot 	
Seguridad	<ul style="list-style-type: none"> Introduction to Cybersecurity 		<ul style="list-style-type: none"> Cybersecurity Essentials 		<ul style="list-style-type: none"> CCNA Cyber Ops CCNA Security 	
IoT y análisis	<ul style="list-style-type: none"> Introduction to IoT 		<ul style="list-style-type: none"> IoT Fundamentals: Connecting Things, Big Data & Analytics, IoT Security* Hackathon Playbook 			
SO y TI	<ul style="list-style-type: none"> NDG Linux Unhatched 		<ul style="list-style-type: none"> NDG Linux Essentials IT Essentials 		<ul style="list-style-type: none"> NDG Linux I NDG Linux II 	
Programación			<ul style="list-style-type: none"> CLA: Programming Essentials in C CPA: Programming Essentials in C++ PCAP: Programming Essentials in Python Talleres de tecnología emergente: Experimentando con API REST utilizando Cisco Spark* 		<ul style="list-style-type: none"> CLP: Advanced Programming in C* CPP: Advanced Programming in C++ 	
Laboral	<ul style="list-style-type: none"> Be Your Own Boss 		<ul style="list-style-type: none"> Entrepreneurship 			
Instrucción digital	<ul style="list-style-type: none"> Get Connected 					

El portafolio educativo de Networking Academy

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Seguridad	<ul style="list-style-type: none"> Introduction to Cybersecurity 		<ul style="list-style-type: none"> Cybersecurity Essentials 		<ul style="list-style-type: none"> CCNA Cyber Ops CCNA Security 	
IoT y análisis	<ul style="list-style-type: none"> Introduction to IoT 		<ul style="list-style-type: none"> IoT Fundamentals: Connecting Things, Big Data & Analytics, IoT Security* Hackathon Playbook 			
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Instrucción digital	<ul style="list-style-type: none"> Get Connected 					



PCAP: Programming Essentials in Python





	To do	Doing	Done

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- 1.- Introducción
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PCAP: Programming Essentials in Python

Descripción general del curso

Diseñado para ser un curso fácil de entender y sencillo para principiantes, centrado en diversos tipos de recopilación de datos, herramientas de manipulación y operaciones de lógica y bit, y en la creación de API REST básicas.

Beneficios

Con PCAP: Programming Essentials in Python, aprenderá a diseñar, escribir, depurar y ejecutar programas codificados en el lenguaje Python. No se requiere ningún conocimiento previo de programación. El curso comienza con una orientación básica paso a paso hasta que se vuelva experto en resolver problemas más complejos.

Componentes educativos

- 5 módulos de contenido instructivo interactivo
- Más de 30 prácticas de laboratorio incluidas
- Herramienta en línea integrada para realizar prácticas de laboratorio
- Quizzes y Tests de evaluación por módulo y sección
- Test de evaluación final



 Coordinado con la certificación

Características

Público objetivo: estudiantes de secundaria y terciarios

Requisitos previos: ninguno

Requiere capacitación a cargo de instructor: no

Idiomas: inglés

Presentación del curso: con instructor

Tiempo estimado para completar el curso: 60 a 70 horas

Próximo curso recomendado: IoT Fundamentals, Networking Essentials, NDG Linux Essentials

Programming Essentials in Python



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con
OpenEDG Python Institute

Course Syllabus

El curso está formado por **5 módulos** con contenido interactivo, distribuidos en dos partes o secciones (*Basics e Intermediate*).

Introduction

Module 0

Part I: Basics

Module 1: Basics I

Module 2: Basics II

Module 3: Basics II

Part II: Intermediate

Module 4: Intermediate I

Module 5: Intermediate II

Programming Essentials in Python



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con OpenEDG Python Institute

Edube Sandbox

Herramienta en línea integrada en el propio navegador web que ofrece un interprete de Python.



<https://edube.org/sandbox?language=python>

```
▶ ↺ ⬇ 📁 ↶ 📌 ⚙️
1 import random as rnd
2
3 def max(op1, op2):
4     return op1 if (op1 >= op2) else op2
5
6 def min(op1, op2):
7     return op1 if (op1 <= op2) else op2
8
9
10 a = rnd.randint(1, 100)
11 b = rnd.randint(1, 100)
12 print("MAX({}, {}) = {}".format(a, b, max(a,b)))
13 print("MIN({}, {}) = {}".format(a, b, min(a,b)))
```

Console >_

Clear

```
MAX(9, 43) = 43
MIN(9, 43) = 9
```

Programming Essentials in Python



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con OpenEDG Python Institute

Edube Labs

El curso contiene más de **30 prácticas o laboratorios** con soluciones incluidas.

The screenshot shows the Edube Labs interface for a lab titled "1.1.4.1 The print() function". The interface includes a navigation menu, a sidebar with "Lab Assignments", and a main content area with the following details:

- Navigation:** PYTHON INSTITUTE
- Lab Title:** 1.1.4.1 The print() function
- Lab Assignments:** Sidebar menu
- Estimated time:** 5 minutes
- Level of difficulty:** Very easy
- Objectives:**
 - becoming familiar with the `print()` function and its formatting capabilities;
 - experimenting with Python code.
- Scenario:**

The `print()` command, which is one of the easiest directives in Python, simply prints out a line to the screen, in your first lab:

 - Use the `print()` function to print the line "Hello, Python!" to the screen.
 - Having done that, use the `print()` function again, but this time print your first name.
 - Remove the double quotes and run your code. Watch Python's reaction. What kind of error is thrown?
 - Then, remove the parentheses, put back the double quotes, and run your code again. What kind of error is thrown at this time?
 - Experiment as much as you can. Change double quotes to single quotes, use multiple `print()` functions on the same line, and then on different lines. See what's going on. If you want to finish the lab, just print "Goodbye, Python!" to the screen.
- Lab Instructions:** Bottom right of the content area
- Editor/Console:** Bottom right of the interface

Estimated time

30-45 minutes

Level of difficulty

Hard

Objectives

- improving the student's skills in operating with strings and lists;
- converting strings into lists.

Scenario

As you probably know, Sudoku is a number-placing puzzle played on a 9x9 board. The player has to fill the board in a very specific way:

- each row of the board must contain all digits from 0 to 9 (the order doesn't matter)
- each column of the board must contain all digits from 0 to 9 (again, the order doesn't matter)
- each of the nine 3x3 "tiles" (we will name them "sub-squares") of the table must contain all digits from 0 to 9.

If you need more details, you can find them [here](#).

Your task is to write a program which:

- reads 9 rows of the Sudoku, each containing 9 digits (check carefully if the entered data are valid)
- outputs "Yes" if the Sudoku is valid, and "No" otherwise.

Test your code using the data we've provided.

Example input

```
295743861 431865927 876192543 387459216 612387495 549216738 763524189 928671354 154938672
```

Example output

Yes

Example input

```
195743862 431865927 876192543 387459216 612387495 549216738 763524189 928671354 254938671
```

Example output

No

1

Console >_

Programming Essentials in Python



Programación

PCAP: Programming Essentials in Python

Por Cisco Networking Academy, en colaboración con OpenEDG Python Institute

Modelo de evaluación

El curso contiene una serie de **quizzes** de preparación y **tests** de evaluación para cada módulo y sección.

Además existe un **test de evaluación final**.

 **Module 1 Test**
20 ptos. | 20 preguntas

 **Module 2 Test**
20 ptos. | 20 preguntas

 **Module 3 Test**
20 ptos. | 20 preguntas

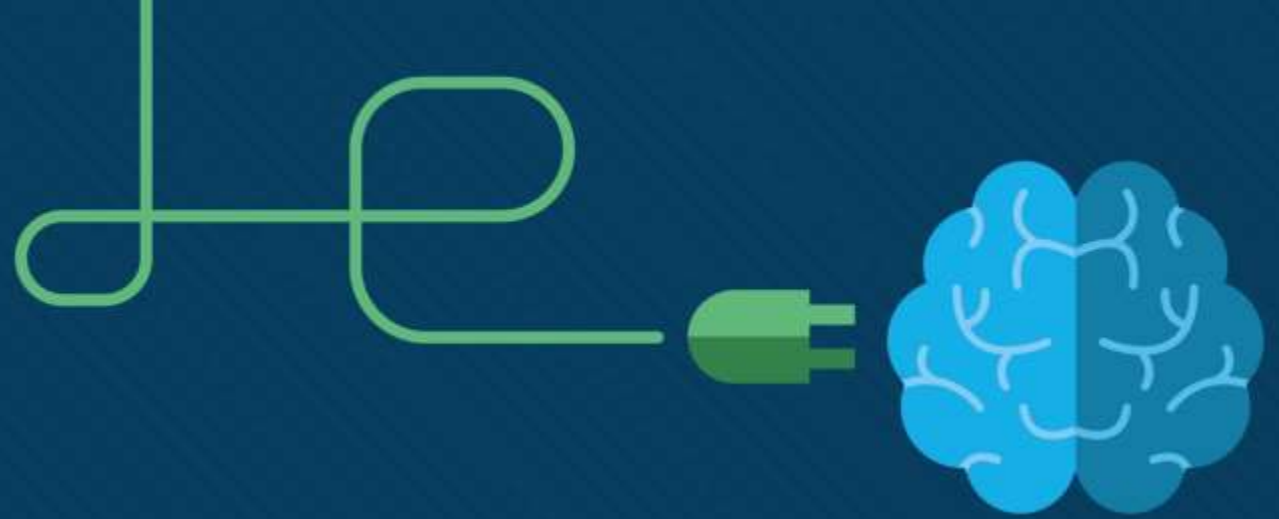
 **Module 4 Test**
20 ptos. | 20 preguntas

 **Module 5 Test**
30 ptos. | 30 preguntas

 **Summary Test 1**
30 ptos. | 30 preguntas

 **Summary Test 2**
30 ptos. | 30 preguntas

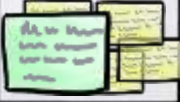

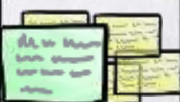

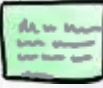

 **Final Test**
50 ptos. | 50 preguntas



PCAP: Demo del curso





To do	Doing	Done
		
		
		
		
		
		

Agenda

- 1.- Introducción
- 2.- Python en la actualidad
- 3.- CNA: Portfolio educativo
- 4.- PCAP: Programming Essentials in Python
- 5.- PCAP: Demo del curso**
- 6.- Hands-On Labs

Una oportunidad de por vida

Durante 20 años, Cisco Networking Academy les ha cambiado la vida a 9.2 millones de estudiantes en 180 países al ofrecerles educación, capacitación técnica y orientación en desarrollo profesional.

Meet Soso



Una oportunidad increíble lo está esperando. La tecnología está cambiando el mundo porque conecta miles de millones de dispositivos y mejora nuestra forma de vivir, trabajar, jugar y tratar a nuestro planeta. Ninguna industria es inmune. ¿Está listo para cambiar su vida y, posiblemente, hacer del mundo un lugar mejor?



Networking



Internet of Things



Programming



Security



OS & IT



Packet Tracer



Página de inicio

Módulos

Evaluaciones

Foros

Personas


Mi NetAcad


Cuenta


Tablero


Cursos


Calendario


Bandeja de entrada


Ayuda

▸ Welcome to PCAP | Programming Essentials in Python

Complete todos los elementos



▸ Edube | Sandbox and Lab Tool

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python

▸ Part 1: BASICS

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python

▸ Part 1 Summary Test

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python

Complete todos los elementos

▸ Part 2: INTERMEDIATE

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python, Part 1 Summary Test



▸ Part 2 Summary Test

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python, Part 1 Summary Test

Complete todos los elementos



▸ Final Test

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python, Part 2 Summary Test

Complete todos los elementos



▸ Course Completion Voucher

Prerrequisitos: Welcome to PCAP | Programming Essentials in Python, Final Test



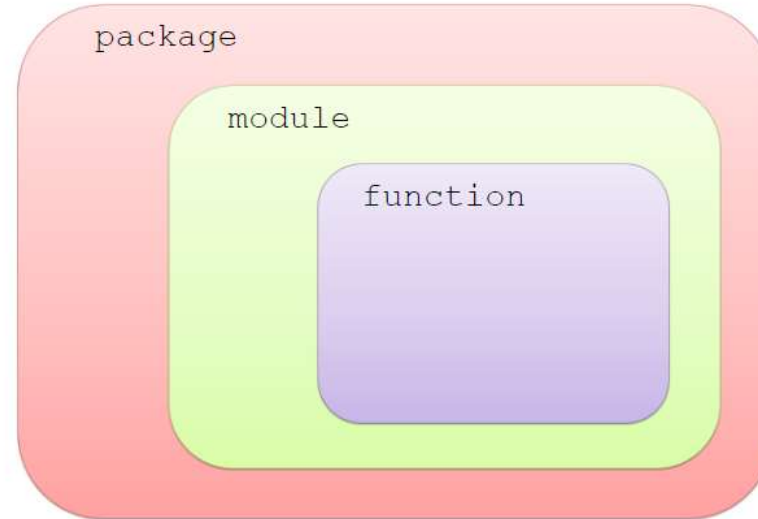


4.3.1 Modules and packages

Writing your own modules doesn't differ much from writing ordinary scripts. There are some specific aspects you must be aware of, but it definitely isn't rocket science. You'll see this soon enough.

Let's summarize some important issues:

- a module is a **kind of container** filled with functions – you can pack as many functions as you want into one module and distribute it across the world;
- of course, it's generally a good idea **not to mix** functions with different application areas within one module (just like in a library – nobody expects scientific works to be put among comic books), so group your functions carefully and name the module containing them in a clear and intuitive way (e.g., don't give the name `arcade_games` to a module containing functions intended to partition and format hard disks)
- making many modules may cause a little mess – sooner or later you'll want to **group** your modules exactly in the same way as you've previously grouped functions – is there a more general container than a module?
- yes, there is – it's a **package**; in the world of modules, a package plays a similar role to a folder/directory in the world of files.





4.3.15 Your first package

Suddenly, somebody notices that these modules form their own hierarchy, so putting them all in a flat structure won't be a good idea.

After some discussion, the team comes to the conclusion that the modules have to be grouped. All participants agree that the following tree structure perfectly reflects the mutual relationships between the modules →

Let's review this from the bottom up:

- the `ugly` group contains two modules: `psi` and `omega`;
- the `best` group contains two modules: `sigma` and `tau`;
- the `good` group contains two modules (`alpha` and `beta`) and one subgroup (`best`)
- the `extra` group contains two subgroups (`good` and `bad`) and one module (`iota`)

Does it look bad? Not at all – analyze the structure carefully. It resembles something, doesn't it?

It looks like a directory structure.





5.5.6 Inheritance – why and how?

Read the code carefully →

There are two nested loops. Their purpose is to check all possible ordered pairs of classes, and to print the results of the check to determine whether the pair matches the subclass-superclass relationship.

The program produces the following output:

```
True False False True True False True True
True
```

Let's make the result more readable:

↓ is a subclass of →	Vehicle	LandVehicle	TrackedVehicle
Vehicle	True	False	False
LandVehicle	True	True	False
TrackedVehicle	True	True	True

There is one important observation to make: **each class is considered to be a subclass of itself.**

```
class Vehicle:
    pass

class LandVehicle(Vehicle):
    pass

class TrackedVehicle(LandVehicle):
    pass

for cl1 in [Vehicle, LandVehicle, TrackedVehicle]:
    for cl2 in [Vehicle, LandVehicle, TrackedVehicle]:
        print(issubclass(cl1,cl2),end='\t')
    print()
```

[Download 5.5.6.py](#)





1.1.23 The print() function

```
My_name_is*Monty*Python*
```

This is how it looks now →

Now that you understand the `print()` function, you're ready to consider how to store and process data in Python.

Without `print()`, you wouldn't be able to see any results.

Practice Labs

- Lab PCA_1_1_23_1_A *The print() function:*
[Launch in Edube](#) | [Launch Sample Solution](#)
- Lab PCA_1_1_23_2_A *Formatting the output:*
[Launch in Edube](#) | [Launch Sample Solution](#)





Estimated time

5-10 minutes

Level of difficulty

Easy

Objectives

- experimenting with existing Python code;
- discovering and fixing basic syntax errors;
- becoming familiar with the `print()` function and its formatting capabilities.

Scenario

We strongly encourage you to play with the code we've written for you, and make some (maybe even destructive) amendments. Feel free to modify any part of the code, but there is one condition - learn from your mistakes and draw your own conclusions.

Try to:

- minimize the number of `print()` function invocations by inserting the `\n` sequence into the strings
- make the arrow twice as large (but keep the proportions)
- duplicate the arrow, placing both arrows side by side; note: a string may be multiplied by using the following trick:
`"string" * 2`
 will produce `"stringstring"` (we'll tell you more about it soon)
- remove any of the quotes, and look carefully at Python's response; pay attention to where

```

1 print("  *")
2 print(" * *")
3 print(" * *")
4 print(" * *")
5 print("*** **")
6 print(" * *")
7 print(" * *")
8 print(" *****")

```

Console >_



SAMPLE SOLUTION: This is only an example of how you can do the lab. Sometimes, there may be multiple ways to do an exercise, and the solution here may not necessarily be the only, or even the best, way.

Estimated time

5-10 minutes

Level of difficulty

Easy

Objectives

- experimenting with existing Python code;
- discovering and fixing basic syntax errors;
- becoming familiar with the `print()` function and its formatting capabilities.

Scenario

We strongly encourage you to play with the code we've written for you, and make some (maybe even destructive) amendments. Feel free to modify any part of the code, but there is one condition - learn from your mistakes and draw your own conclusions.

Try to:

- minimize the number of `print()` function invocations by inserting the `\n` sequence into the strings
- make the arrow twice as large (but keep the proportions)



```

1 # Sample Solution
2
3 #####
4 print("original version:")
5 #####
6 print("  *")
7 print(" * *")
8 print(" * *")
9 print(" * *")
10 print("*** **")
11 print(" * *")
12 print(" * *")
13 print(" *****")
14 #####
15 print("with fewer 'print()' invocations:")
16 #####
17 print(" * \n * * \n * * * \n * * * * \n * * * * *")
18 print(" * * \n * * * \n * * * *")
19 #####
20 print("higher:")
21 #####
22 print("  *")
23 print(" * *")
24 print(" * *")
25 print(" * *")
26 print(" * *")
27 print(" * *")
28 print(" * *")
29 print(" * *")
30 print("*****")
31 print(" * *")
32 print(" * *")

```

Console >_





Lab 3.3.12.2 Writing and using your own functions -

basics:

[Open in the online simulator](#)

[Download a PDF](#)

Lab 3.3.12.3 Writing and using your own functions -

basics:

[Open in the online simulator](#)

[Download a PDF](#)

Lab 3.3.12.4 Prime numbers - how do we find them?

[Open in the online simulator](#)

[Download a PDF](#)

```
def strangelist(n):  
    list = [ ]  
    for i in range(0,n):  
        list.insert(0,i)  
    return list  
  
print(strangelist(5))
```





Estimated time

10-20 minutes

Level of difficulty

Medium

Objectives

- improving the student's skills in operating with strings;
- using built-in Python string methods.

Scenario

You already know how the `split()` works. Now we want you to prove it.

Your task is to write your own function, which behaves almost exactly like the original `split()` method, i.e:

- it should accept exactly one argument – a string;
- it should return a list of words created from the string, divided in the places where the string contains white spaces;
- if the string is empty, the function should return an empty list;
- its name should be `mysplit()`

Use the template presented below. Test your code carefully.

```
1 def mysplit(strng):
2     #
3     # put your code here
4     #
5
6     print(mysplit("To be or not to be, that is the question"))
7     print(mysplit("To be or not to be,that is the question"))
8     print(mysplit(" "))
9     print(mysplit(" abc "))
10    print(mysplit(""))
```

Console >_





decimal digit using a subset of seven segments. If you still don't know what it is, refer to the following Wikipedia [article](#).

Your task is to write a program which is able to simulate the work of a seven-display device, although you're going to use single LEDs instead of segments. Each digit is constructed from 13 LEDs (some lit, some dark, of course) - that's how we imagine it:

Note: the number 8 shows all the LED lights on.

Your code has to *display* any non-negative integer number entered by the user.

Hint: using a list containing patterns of all ten digits may be very helpful.

Example input

123

Example output

#####

Example input

9081726354

Example output

#####

```
1 # ### ## # # ## ## ## ## ## ##
2 # # # # # # # # # # # #
3 # ### ## ## ## ## # ## ## # #
4 # # # # # # # # # # # #
5 # ### ## # ## ## # ## ## ##
```

Console >_



Show chapters

Module 4 Quiz

1



Module 4 Quiz

Welcome to the Module 4 Quiz!

This quiz will help you prepare for the Module 4 Test. You will have 25 minutes to answer 10 questions, and you will be able to see the correct answers after you submit the quiz. You are free to take the quiz as many times as you like.

Please allow a few seconds for the quiz to load.



Module 4 Quiz

This quiz will help you prepare for the Module 4 Test. You will have 25 minutes to answer 10 questions. Click *Start Quiz* to begin. Good luck!

Start Quiz



Show chapters

Module 4 Quiz

1



Module 4 Quiz

Welcome to the Module 4 Quiz!

This quiz will help you prepare for the Module 4 Test. You will have 25 minutes to answer 10 questions, and you will be able to see the correct answers after you submit the quiz. You are free to take the quiz as many times as you like.

Please allow a few seconds for the quiz to load.

Question 2 of 10

Point Value: 1

Total Points: 0 out of 10

 24:41

If you want to import *pi* from *math*, you'd use:

- import pi from math
- from pi import math
- from math import pi

Submit

Show chapters

Module 4 Quiz

1



Module 4 Quiz

Welcome to the Module 4 Quiz!

This quiz will help you prepare for the Module 4 Test. You will have 25 minutes to answer 10 questions, and you will be able to see the correct answers after you submit the quiz. You are free to take the quiz as many times as you like.

Please allow a few seconds for the quiz to load.

Question 2 of 10

Point Value: 1

Total Points: 1 out of 10

 23:47

If you want to import *pi* from *math*, you'd use:

- import pi from math
- from pi import math
- from math import pi

Correct

That's right! You answered correctly.

Continue





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[Personas](#)

▼ Evaluaciones para tareas



Final Test

50 ptos. | 50 preguntas



Module 1 Test

20 ptos. | 20 preguntas



Module 2 Test

20 ptos. | 20 preguntas



Module 3 Test

20 ptos. | 20 preguntas



Module 4 Test

20 ptos. | 20 preguntas



Module 5 Test

30 ptos. | 30 preguntas



Summary Test 1

30 ptos. | 30 preguntas



Summary Test 2

30 ptos. | 30 preguntas



- Mi NetAcad
- Cuenta
- Tablero
- Cursos
- Calendario
- Bandeja de entrada
- Ayuda

[Página de inicio](#)

[Módulos](#)

Evaluaciones

[Foros](#)

[Personas](#)

Module 3 Test

Fecha límite No hay fecha límite	Puntos 20	Preguntas 20	Tiempo límite 30 minutos
Intentos permitidos 30			

Instrucciones

Number of questions: **20**

Time limit: **30 minutes**

Allowed attempts: **3**

See Correct Answers: **Yes** (after the last attempt)

Points to score: **20** (each question is worth 1 point)

Passing score: **No**

Realizar la evaluación

[◀ Anterior](#)

[Siguiente ▶](#)

See Correct Answers: **Yes** (after the last attempt)

Points to score: **20** (each question is worth 1 point)

Passing score: **No**

Tiempo de ejecución: [Esconder](#)
29 minutos, 24 segundos


Mi NetAcad


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Calendario


Bandeja de
entrada


Ayuda



Pregunta 2

1 ptos.

A function defined in the following way:

```
def function(x=0):  
    return x
```

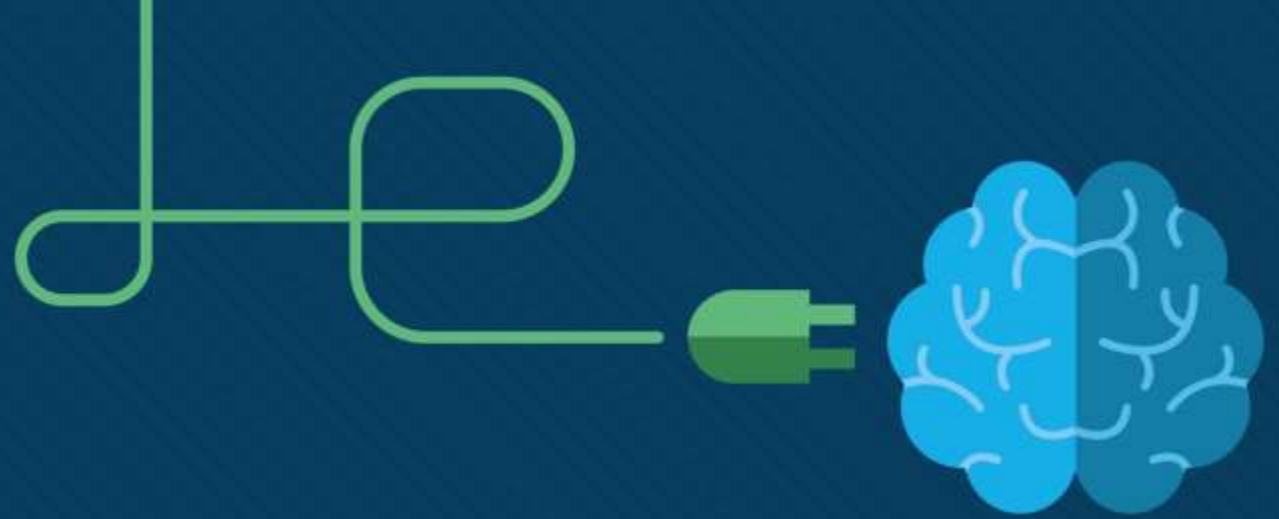
- may be invoked without any argument, or with just one
- may be invoked with any number of arguments (including zero)
- must be invoked with exactly one argument
- must be invoked without arguments

◀ Anterior

Siguiente ▶

No guardado

Entregar evaluación



Hands-On Labs

Una introducción práctica al procesamiento de imágenes y la visión artificial con Python



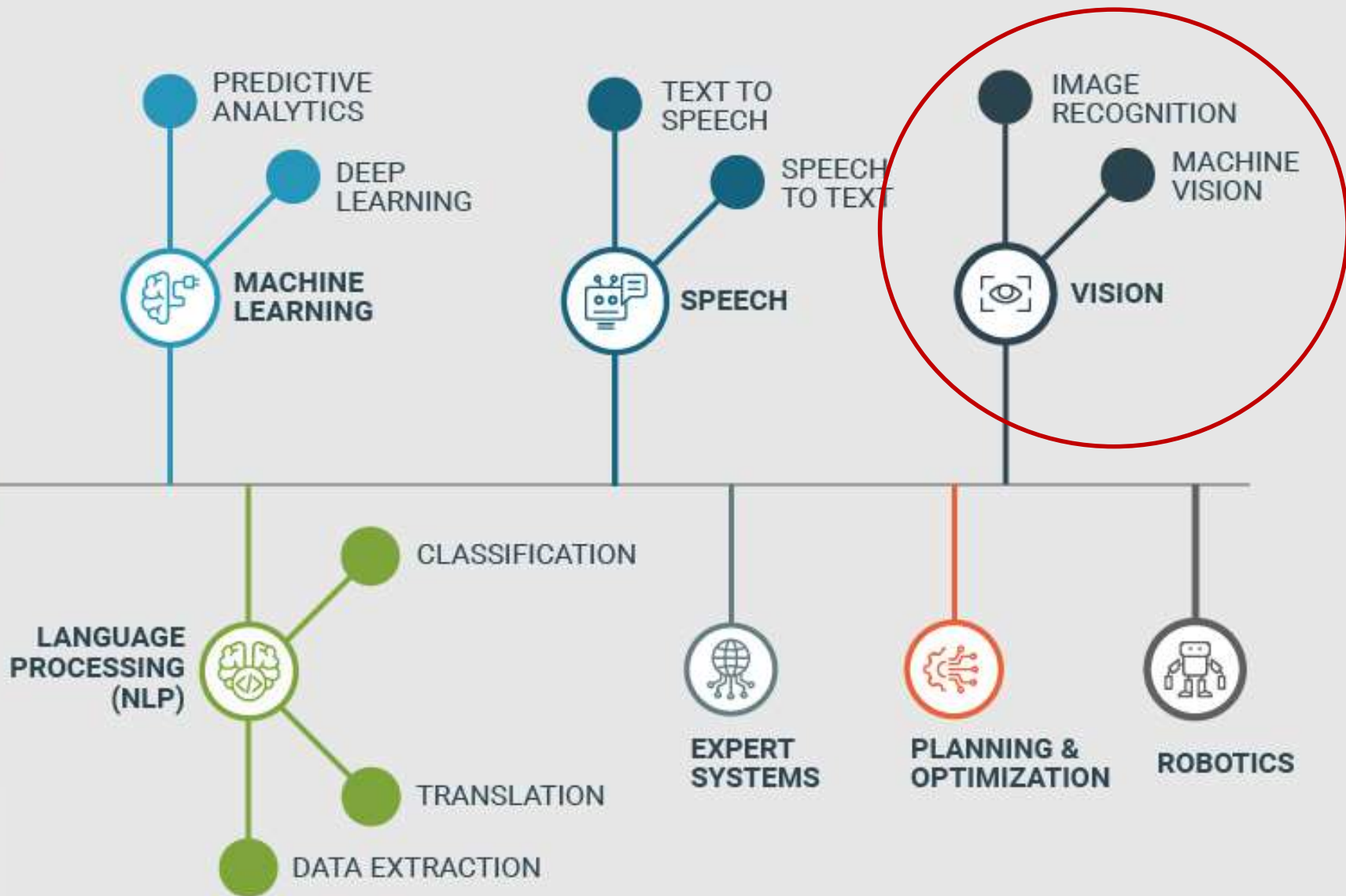


To do	Doing	Done

Agenda

- 1.- Introducción
- 2.- Python en la actualidad
- 3.- CNA: Portfolio educativo
- 4.- PCAP: Programming Essentials in Python
- 5.- PCAP: Demo del curso
- 6.- Hands-On Labs**

ARTIFICIAL INTELLIGENCE



Conseguir que las máquinas imiten el sistema de visión humano
Resolver el problema de interpretar de forma automática el contenido de las imágenes y vídeos

Vehicles: 6

Speeding: 10%

Moving: 4

People: 65

NEWSIES

Photo

traffic: 19 inside: 2

MAC

traffic: 7 inside: 0

Disney

traffic: 30 inside: 11

Forever21

traffic: 10 inside: 0

car

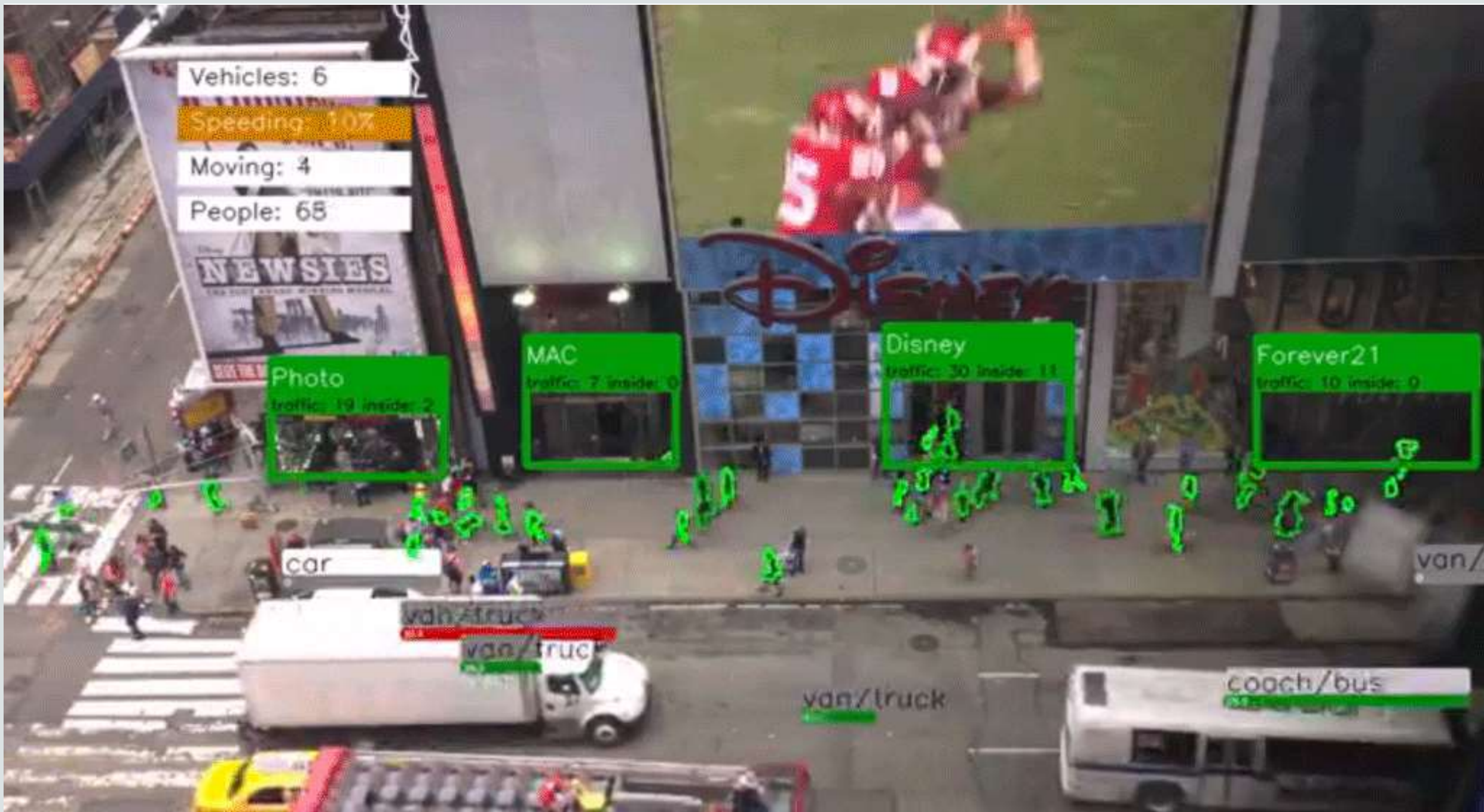
van/truck

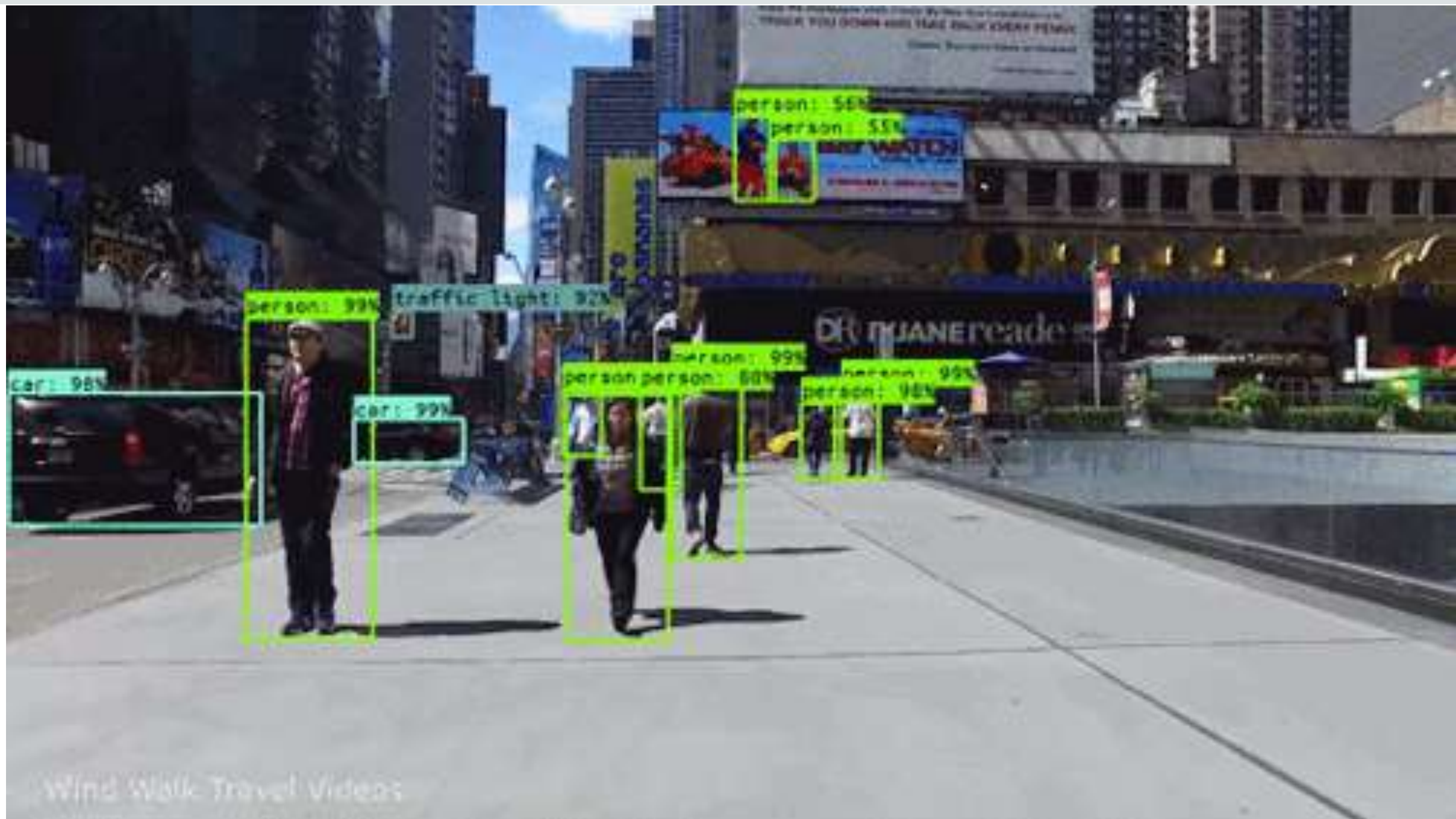
van/truc

van/truck

coach/bus

van/







OpenCV 4.1 is here

The most popular computer vision library just got better

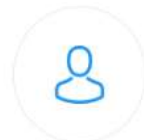
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Hands-On Labs



```
> pip install opencv-contrib-python
```

```
Collecting opencv-contrib-python
```

```
Using cached
```

```
https://files.pythonhosted.org/packages/aa/4c/a3125e25da4b121b4077c575eee8a691ffabb5d97afc5ae832fd5a7015e3/opencv_contrib_python-4.1.0.25-cp37-cp37m-win32.whl
```

```
Collecting numpy>=1.14.5 (from opencv-contrib-python)
```

```
Using cached
```

```
https://files.pythonhosted.org/packages/ab/75/9ac63977cbca68e17406a53a8c573a925a16771800be47a73f18c838f3fb/numpy-1.16.3-cp37-cp37m-win32.whl
```

```
Installing collected packages: numpy, opencv-contrib-python
```

```
Successfully installed numpy-1.16.3 opencv-contrib-python-4.1.0.25
```

```
> pip list
```

Package	Version
-----	-----
numpy	1.16.3
opencv-contrib-python	4.1.0.25
pip	19.1
setuptools	40.8.0

<https://pypi.org/project/opencv-contrib-python/>

Hands-On Labs



load_image.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Image Visualizer"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the image using OpenCV
# The cv2.imread function returns a NumPy array representing the image
image = cv2.imread(args["image"])

# Show image info
print(f"Width: {image.shape[1]} pixels")
print(f"Height: {image.shape[0]} pixels")
print(f"Channels: {image.shape[2]}")
```

Hands-On Labs



load_image.py

```
# Display the image to our screen
cv2.imshow(windowName, image)

# Note: OpenCV stores RGB channels in reverse order.
# While we normally think in terms of Red, Green and Blue;
# OpenCV stores them in the following order: Blue, Green and Red
# Get the pixel located at (0,0) represented as a tuple (b,g,r)
copy = image.copy()
(b, g, r) = copy[0, 0]
print(f"Pixel at (0,0) - RGB: ({r}, {g}, {b})")

# Modify the pixel located at (0,0)
copy[0, 0] = (0,0,255)
(b, g, r) = copy[0, 0]
print(f"Pixel at (0,0) - RGB: ({r}, {g}, {b})")

# Use NumPy array slicing capabilities to access larger rectangular
# portions of image
copy [0:100, 0:100] = (0,0,0)

# Write our image to disk
cv2.imwrite("images/demo.jpg", copy)

# Wait for a key press to finish program
cv2.waitKey(0)

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```





Hands-On Labs



load_video.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-v", "--video", required = True,
                help = "path to where the video resides")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Video Visualizer"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                           cv2.WINDOW_FULLSCREEN)

# Loading the video using OpenCV
video = cv2.VideoCapture(args["video"])
```


Hands-On Labs



load_video.py

```
# Display the video to our screen
# Start to lopping over all frames in the video.
# At most basic level, a video is simply a sequence of images together
while video.isOpened():
    (grabbed, frame) = video.read()

    # Display the output
    cv2.imshow(windowName, frame)

    # Wait for a key press to finish program
    key = cv2.waitKey(1)
    if (key in [ord("q"), 27] or
        cv2.getWindowProperty(windowName, cv2.WND_PROP_VISIBLE) < 1) :
        break

# The reference to the video is released
video.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```

01. Usain Bolt



MisterFilOfficial

100m Men

WR	9.69	CR	9.80
----	------	----	------

6.1

Hands-On Labs



load_cam.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-m", "--mirror", required = False,
                action='store_true', help = "enable mirror mode")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Webcam Visualizer"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the webcam image using OpenCV
cam = cv2.VideoCapture(0)
```

Hands-On Labs



load_cam.py

```
# Display the webcam to our screen
# Start to lopping over all frames in the webcam.
# At most basic level, a video is simply a sequence of images together
while True:
    (grabbed, frame) = cam.read()

    # Mirror effect: Flip on Y axis
    if (args["mirror"]):
        frame = cv2.flip(frame,1)

    # Display the output
    cv2.imshow(windowName, frame)

    # Wait for a key press to finish program
    key = cv2.waitKey(1)
    if (key in [ord("q"), 27] or
        cv2.getWindowProperty(windowName,cv2.WND_PROP_VISIBLE) < 1) :
        break

# The reference to the video is released
cam.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```



Hands-On Labs



cam_capture.py

```
# Import the necessary packages
import time
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-m", "--mirror", required = False,
                action='store_true', help = "enable mirror mode")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Webcam Visualizer"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                           cv2.WINDOW_FULLSCREEN)

# Loading the webcam image using OpenCV
cam = cv2.VideoCapture(0)
```

Hands-On Labs



cam_capture.py

```
# Display the webcam to our screen
# Start to lopping over all frames in the webcam.
# At most basic level, a video is simply a sequence of images together
while True:
    (grabbed, frame) = cam.read()

    # Mirror effect: Flip on Y axis
    if (args["mirror"]):
        frame = cv2.flip(frame,1)

    # Display the output
    cv2.imshow(windowName, frame)

    # Wait for a key press to capture a frame or finish the program
    key = cv2.waitKey(1)
    if (key == ord("p")) :
        filename = time.strftime("%Y-%m-%d-%H-%M-%S")
        cv2.imwrite(f"captures/{filename}.png", frame)
    elif (key in [ord("q"), 27] or
          cv2.getWindowProperty(windowName,cv2.WND_PROP_VISIBLE) < 1) :
        break

# The reference to the video is released
cam.release()

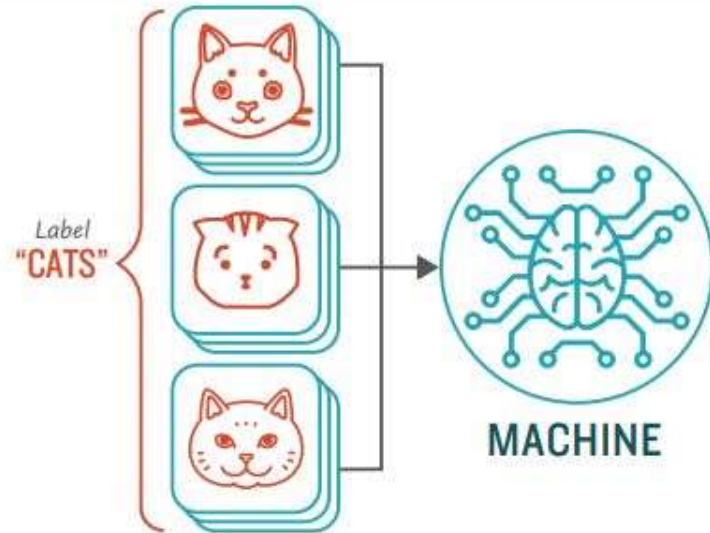
# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```



How **Supervised** Machine Learning Works

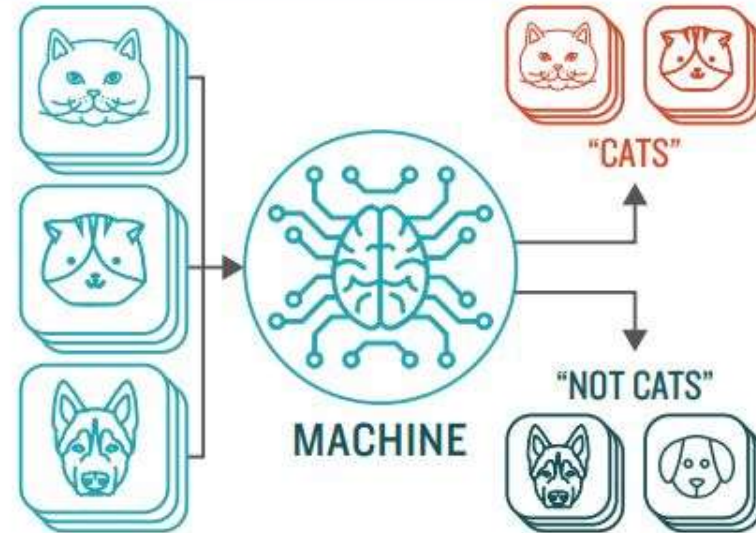
STEP 1

Provide the machine learning algorithm categorized or "labeled" input and output data from to learn

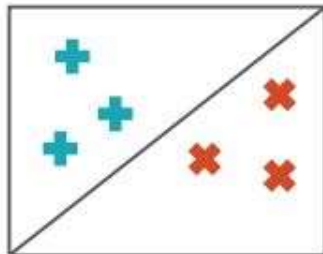


STEP 2

Feed the machine new, unlabeled information to see if it tags new data appropriately. If not, continue refining the algorithm

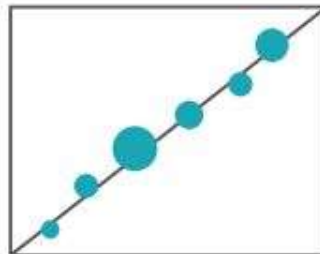


TYPES OF PROBLEMS TO WHICH IT'S SUITED



CLASSIFICATION

Sorting items into categories

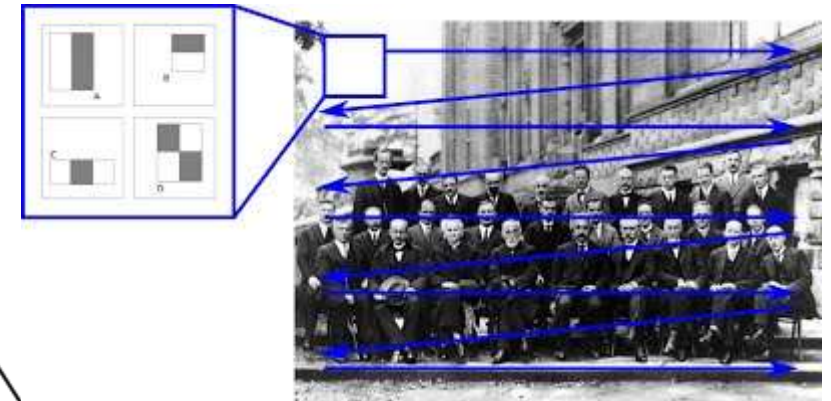
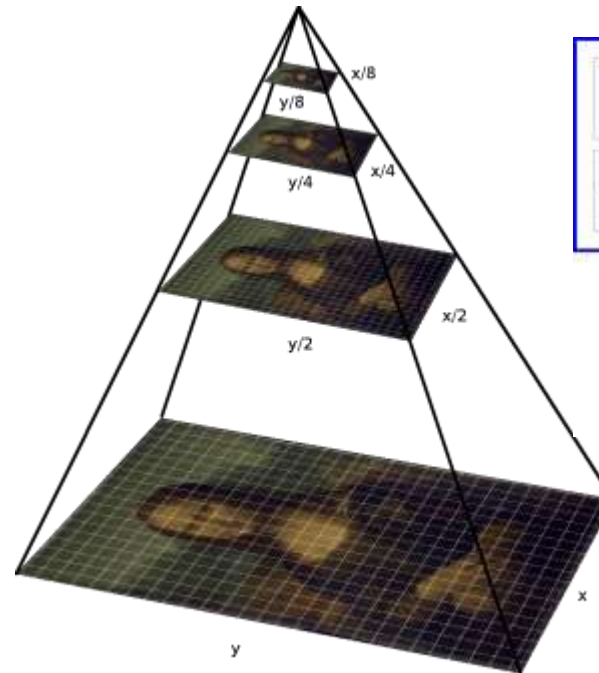
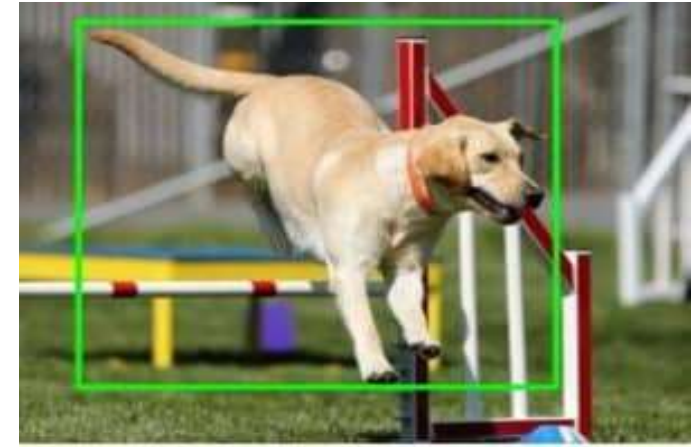
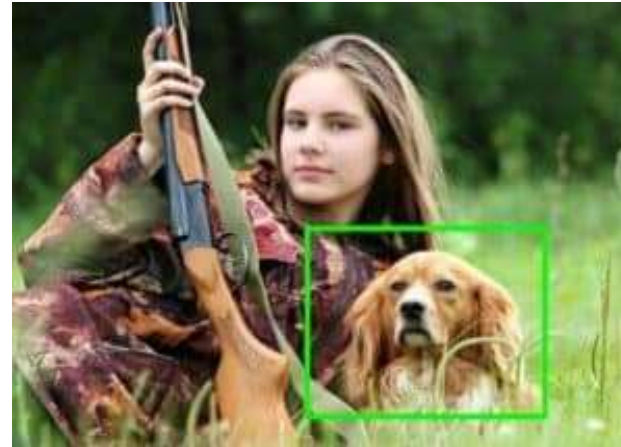


REGRESSION

Identifying real values (dollars, weight, etc.)

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Detección de objetos



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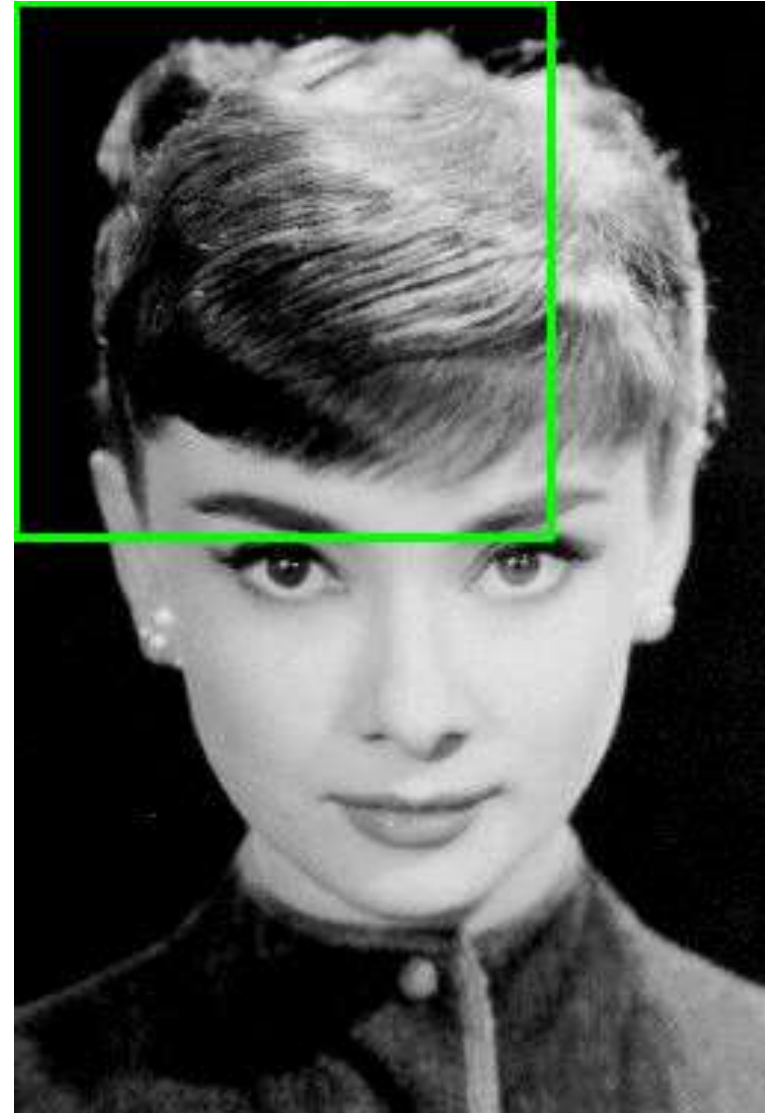
Sliding Window + Image Pyramid



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Sliding Window + Image Pyramid



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Sliding Window + Image Pyramid



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img_faces_detection.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-fc", "--fclassifier", required = False,
                default="classifiers/haarcascade_frontalface.xml",
                help = "path to where the face cascade resides")
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Faces Detector"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the image using OpenCV
image = cv2.imread(args["image"])

# Convert image to grayscale
gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
```

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img_faces_detection.py

```
# In order to build face recognition system, we use the built-in
# Haar cascade classifiers in OpenCV.
# https://github.com/opencv/opencvdata/haarcascades
# This folder contains trained classifiers for detecting objects of a
# particular type, e.g. faces (frontal, profile), pedestrians etc
facesClassifier = cv2.CascadeClassifier("fclassifier")

# "sliding window" approach
# These classifiers work by scanning an image from left to right, and
# top to bottom, at varying scale sizes.
faces = facesClassifier.detectMultiScale(gray, scaleFactor = 1.3,
                                         minNeighbors = 5, minSize = (30,30))

print(f"I found {len(faces)} face(s)")

# loop over the faces and draw a rectangle surrounding each
for (i, (x, y, w, h)) in enumerate(faces):
    cv2.rectangle(image, pt1 = (x, y), pt2 = (x + w, y + h), ...)
    cv2.putText(image, text = f"Face #{i}", org = (x, y - 10), ...)

# Display the image to our screen
cv2.imshow(windowName, image)

# Wait for a key press to finish program
cv2.waitKey(0)

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```



Face #3

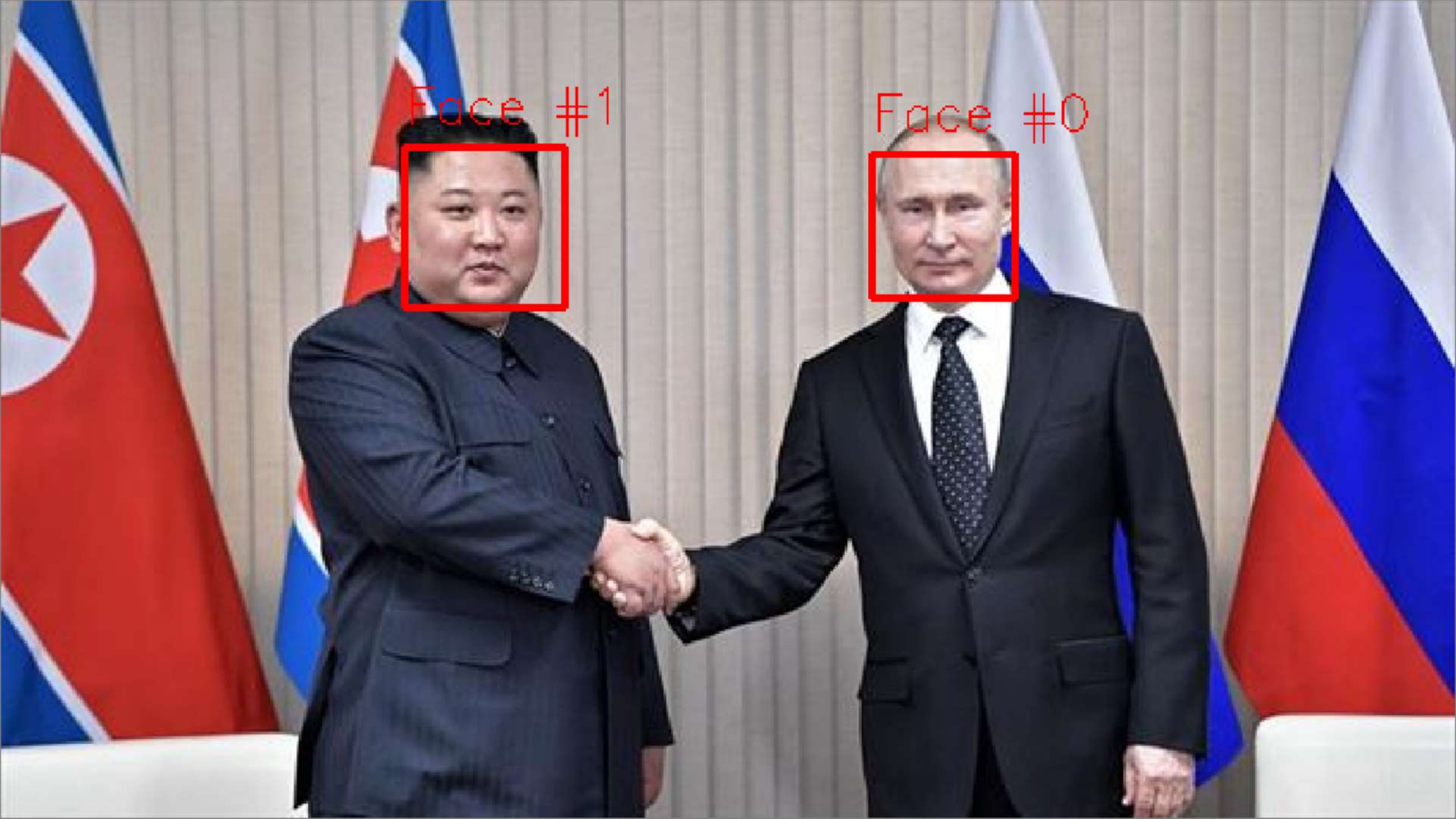
Face #4

Face #1

Face #5

Face #0

Face #2



Face #1

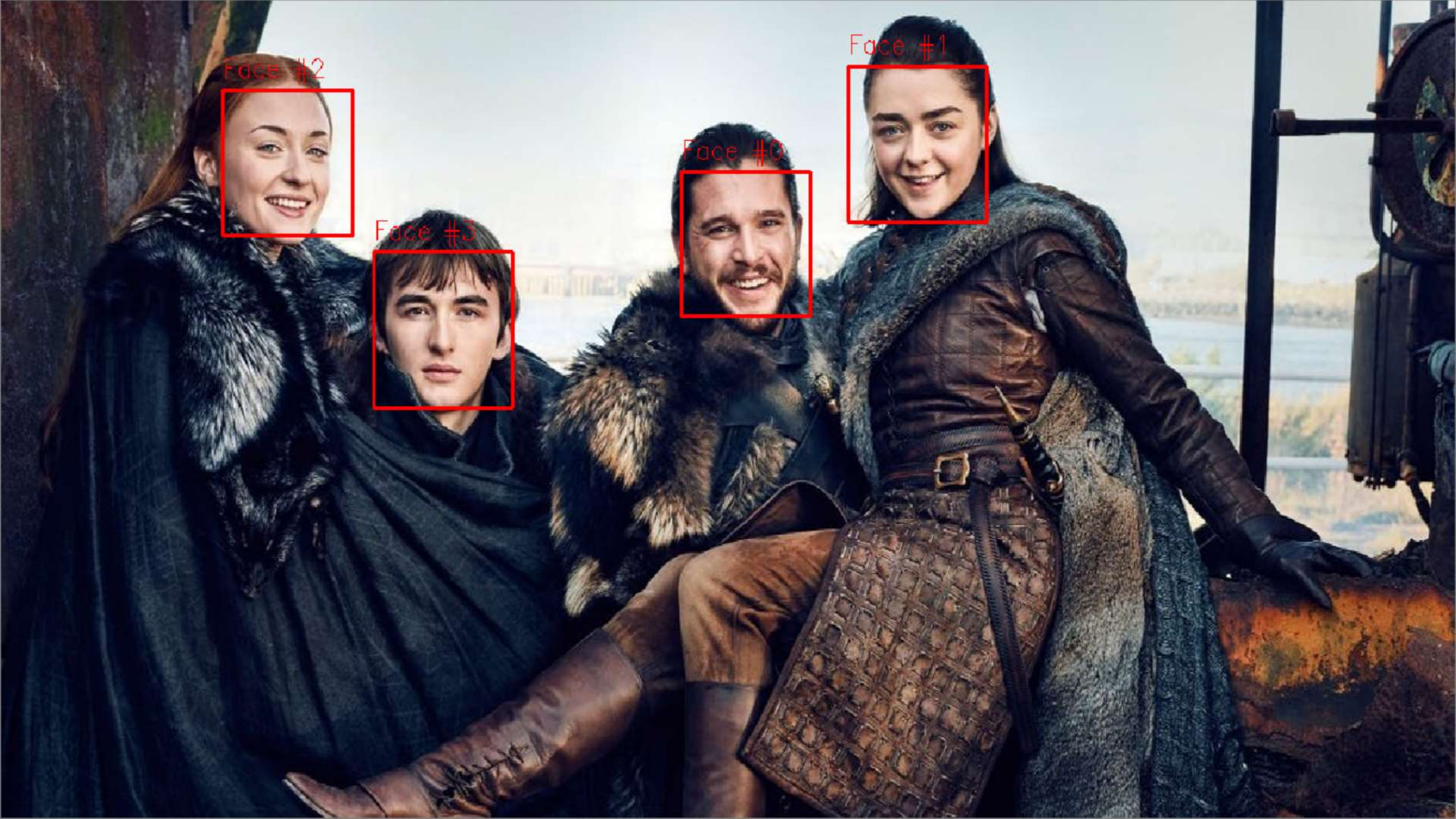
Face #0



Face



Face



Face #2



Face #0



Face #1



Face #1



Face #0





Face #8

Face #10

Face #11

Face #4

Face #6

Face #5

Face #0

Face #7

Face #9

Face #3

Face #1

Face #2

Hands-On Labs



img_cats_detection.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-cc", "--cclassifier", required = False,
                default="classifiers\\haarcascade_frontalcatface.xml",
                help = "path to where the cat cascade resides")
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Cats Detector"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the image using OpenCV
image = cv2.imread(args["image"])

# Convert image to grayscale
gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
```

Hands-On Labs



img_cats_detection.py

```
# In order to build cats recognition system, we use the built-in
# Haar cascade classifiers in OpenCV.
# https://github.com/opencv/opencvdata/haarcascades
# This folder contains trained classifiers for detecting objects of a
# particular type, e.g. faces (frontal, profile), pedestrians etc
catsClassifier = cv2.CascadeClassifier(args["cclassifier"])

# "sliding window" approach
# These classifiers work by scanning an image from left to right, and
# top to bottom, at varying scale sizes.
cats = catsClassifier.detectMultiScale(gray, scaleFactor = 1.05,
                                       minNeighbors = 4, minSize = (30,30))
print(f"I found {len(cats)} cats(s)")

# loop over the cat faces and draw a rectangle surrounding each
for (i, (x, y, w, h)) in enumerate(cats):
    cv2.rectangle(image, pt1 = (x, y), pt2 = (x + w, y + h), ...)
    cv2.putText(image, text = f"Face #{i}", org = (x, y - 10), ...)

# Display the image to our screen
cv2.imshow(windowName, image)

# Wait for a key press to finish program
cv2.waitKey(0)

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```

Cat #1



Cat #2



Cat #0

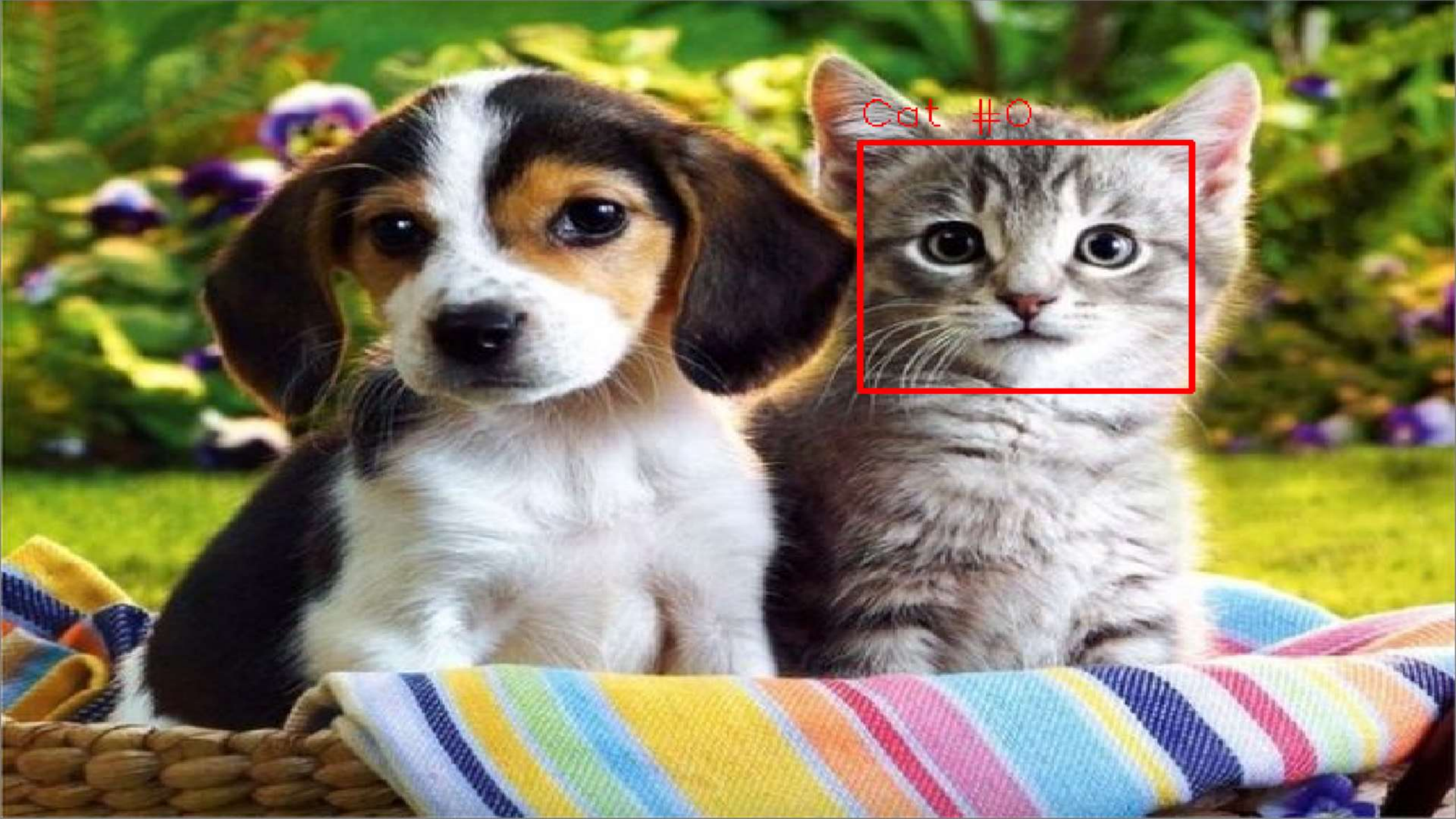


Cat #0



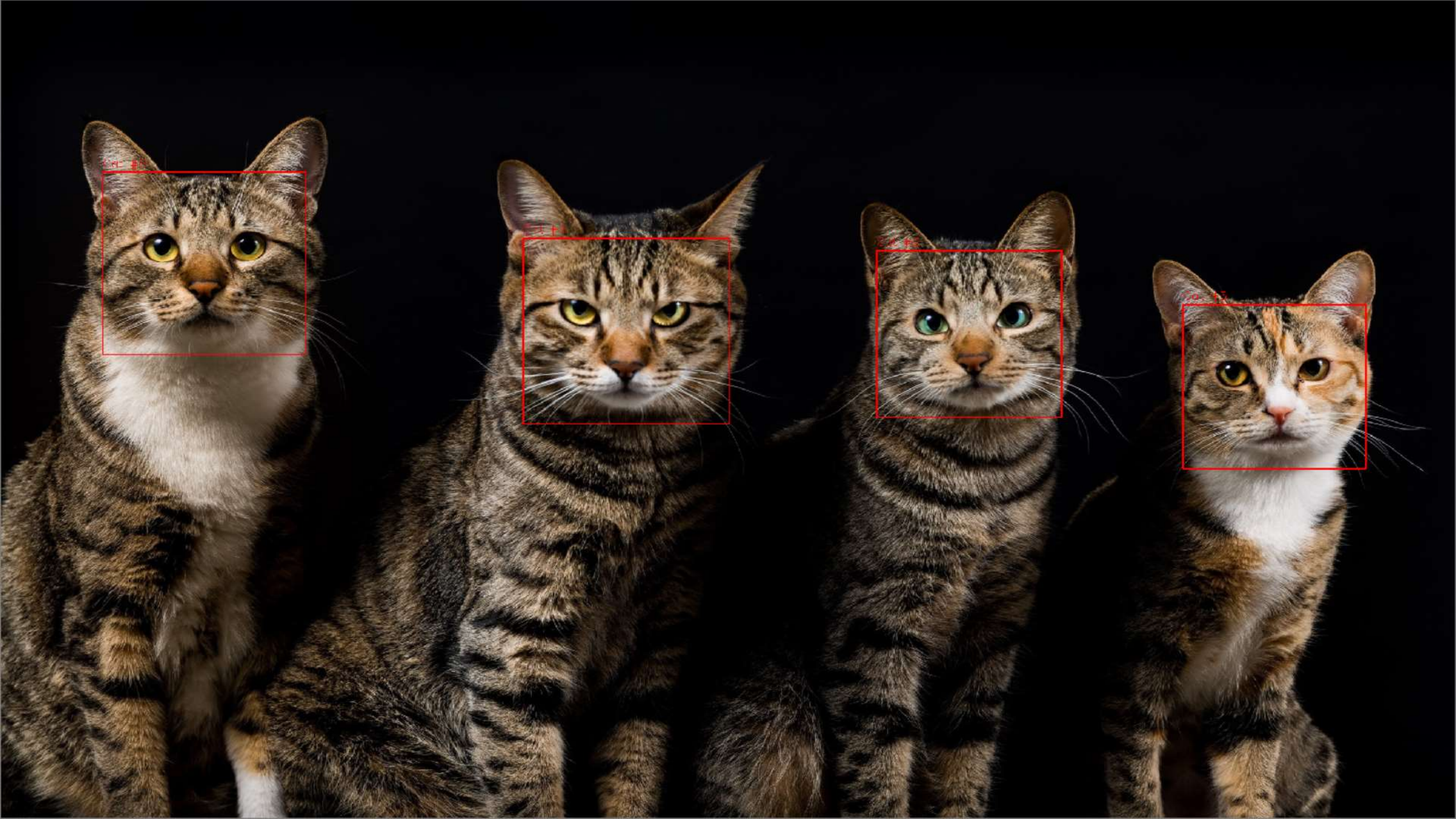
Cat #0

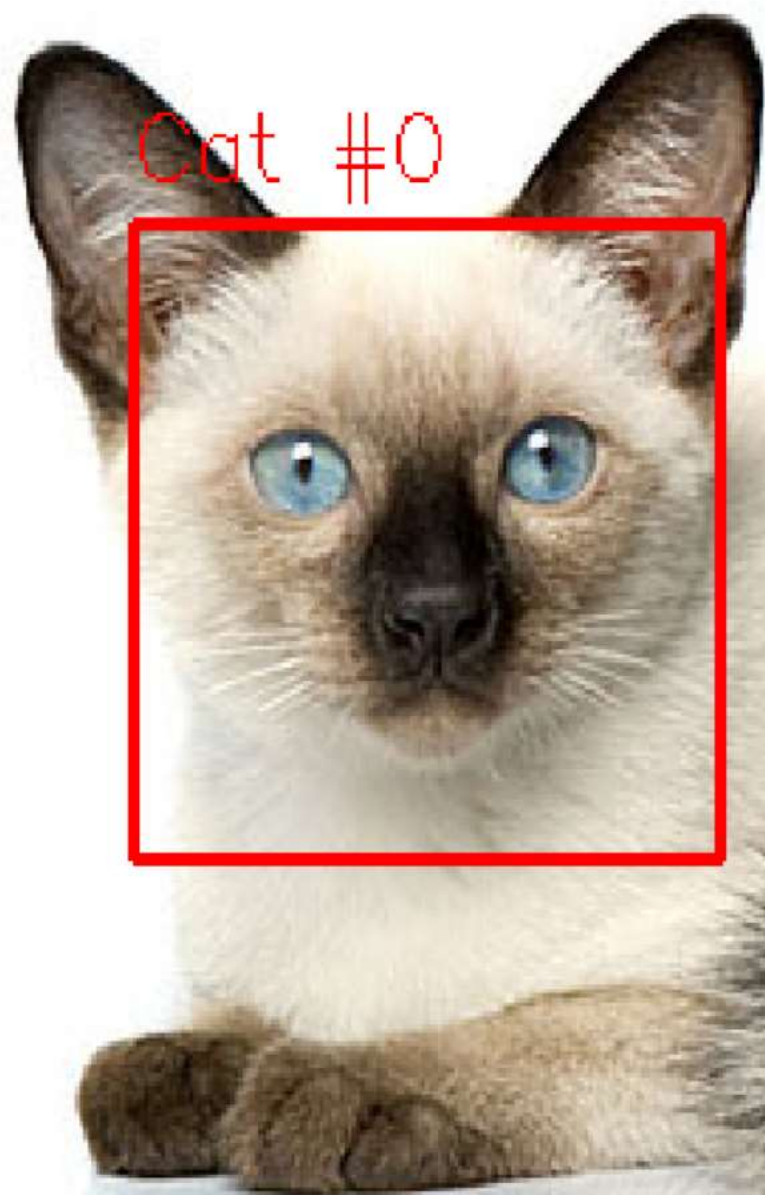




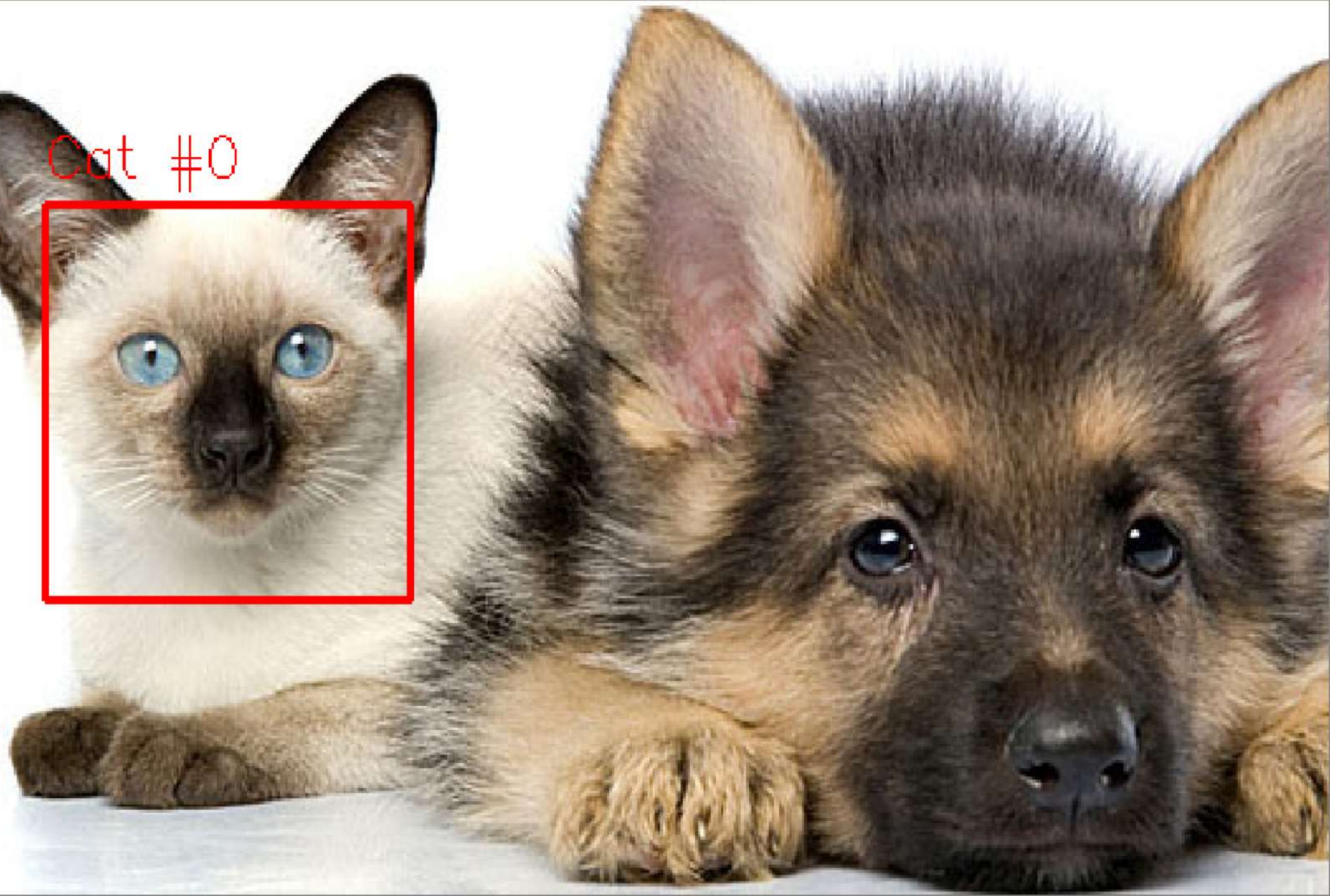
Cat #0







Cat #0



Hands-On Labs



video_faces_detection.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-fc", "--fclassifier", required = False,
                default="classifiers/haarcascade_frontalface_default.xml",
                help = "path to where the face cascade resides")
ap.add_argument("-v", "--video", required = False,
                help = "path to where the video resides")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Video: Cam Detector"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the video using OpenCV
video = cv2.VideoCapture(args["video"])

# Face recognition system: built-in Haar cascade
facesClassifier = cv2.CascadeClassifier(args["fclassifier"])
```

Hands-On Labs



video_faces_detection.py

```
# Start to looping over all frames in the video.
# At most basic level, a video is simply a sequence of images
while video.isOpened():
    # Read next frame
    (grabbed, frame) = video.read()

    # Convert frame to grayscale
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    # Detecting the actual faces in the frame
    faces = facesClassifier.detectMultiScale(gray, scaleFactor =
        1.1, minNeighbors = 5, minSize = (30,30))

    # loop over the faces and draw a rectangle surrounding each
    for (x, y, w, h) in faces:
        cv2.rectangle(frame, pt1 = (x, y), pt2 = (x + w, y + h),
            color = (0, 0, 255), thickness = 2)

    # Display the output
    cv2.imshow(windowName, frame)

    # Wait for a key press to finish program

# The reference to the video is released
video.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```

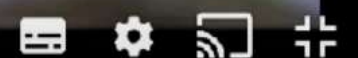


5

Pausa (k)

0:23 / 1:12

Desliza la página para ver más detalles



DIRECTO Plató Debate Atresmedia

EL DEBATE DECISIVO: ÁGIL Y MÁS CONFRONTACIÓN



Hands-On Labs



cam_faces_detection.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-fc", "--fclassifier", required = False,
                default="classifiers/haarcascade_frontalface.xml",
                help = "path to where the face cascade resides")
ap.add_argument("-m", "--mirror", required = False,
                action='store_true', help = "enable mirror mode")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode")
args = vars(ap.parse_args())

# Configure windows
windowName = "Webcam: Face Detector"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)

# Loading the video (webcam) using OpenCV
cam = cv2.VideoCapture(0)

# Face recognition system: built-in Haar cascade
facesClassifier = cv2.CascadeClassifier(args["fclassifier"])
```

Hands-On Labs



cam_faces_detection.py

```
# Start to lopping over all frames in the webcam.
# At most basic level, a video is simply a sequence of images
while True:
    # Read next frame
    (grabbed, frame) = cam.read()

    # Mirror effect: Flip on Y axis
    if (args["mirror"]): frame = cv2.flip(frame,1)
    # Convert frame to grayscale
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    # Detecting the actual faces in the frame
    faces = facesClassifier.detectMultiScale(gray, scaleFactor =
        1.1, minNeighbors = 5, minSize = (30,30))

    # loop over the faces and draw a rectangle surrounding each
    for (x, y, w, h) in faces:
        cv2.rectangle(frame, pt1 = (x, y), pt2 = (x + w, y + h),
            color = (0, 0, 255), thickness = 2)

    # Display the output
    cv2.imshow(windowName, frame)

# The reference to the video is released
cam.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```



Hands-On Labs



eyes_tracking.py

```
# Import the necessary packages
import argparse
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-fc", "--fclassifier", required = False,
                default="classifiers/haarcascade_frontalface_default.xml",
                help = "path to where the face cascade resides (optional)")
ap.add_argument("-ec", "--eclassifier", required = False,
                default="classifiers/haarcascade_eye.xml",
                help = "path to where the eyes cascade resides (optional)")
ap.add_argument("-v", "--video", required = False,
                help = "path to where the video resides (optional)")
ap.add_argument("-m", "--mirror", required = False,
                action='store_true', help = "enable mirror mode (optional)")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode (optional)")
args = vars(ap.parse_args())

# Configure windows
windowName = "Eyes Tracking"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)
```

Hands-On Labs



eyes_tracking.py

```
# If --video is not supplied we will read video from the webcam.
# Otherwise, open the video file pointed by the --video argument
if (args["video"]):
    video = cv2.VideoCapture(args["video"])
else:
    video = cv2.VideoCapture(0)

# In order to build face and eyes recognition system, we use the built-
in Haar cascade classifiers in OpenCV.
facesClassifier = cv2.CascadeClassifier(args["fclassifier"])
eyesClassifier = cv2.CascadeClassifier(args["eclassifier"])

# Display the video or webcam to our screen
while True:
    (grabbed, frame) = video.read()

    # Detect if video finished
    if (args["video"] and not grabbed): break

    # Mirror effect on webcam: Flip on Y axis
    if (not args["video"] and args["mirror"]):
        frame = cv2.flip(frame,1)

    # Convert frame to grayscale
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
```

Hands-On Labs



eyes_tracking.py

```
# Detecting the actual faces in the frame
faces = facesClassifier.detectMultiScale(gray,
    scaleFactor = 1.1, minNeighbors = 5, minSize = (30,30))

# loop over the faces
for (fx, fy, fw, fh) in faces:
    # Draw a rectangle surrounding each
    cv2.rectangle(frame, pt1 = (fx, fy), ...)

    # Extract the face region of interest (ROI)
    faceROI = gray[fy:fy + fh, fx:fx + fw]

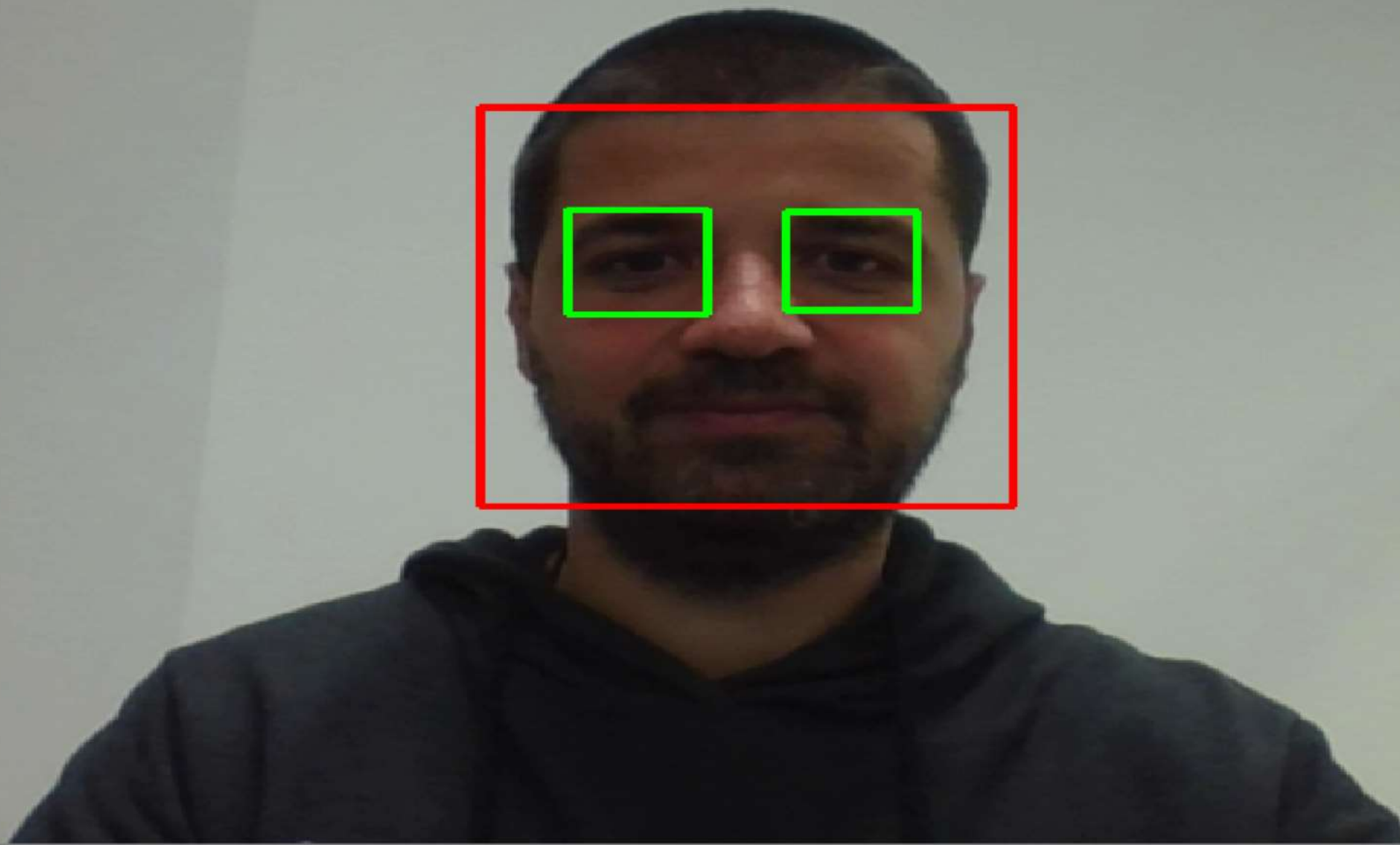
    # Detecting the actual eyes in the frame
    eyes = eyesClassifier.detectMultiScale(faceROI,
    scaleFactor = 1.1, minNeighbors = 10, minSize = (20,20))

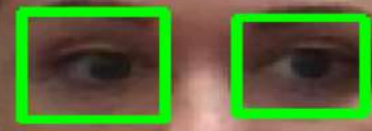
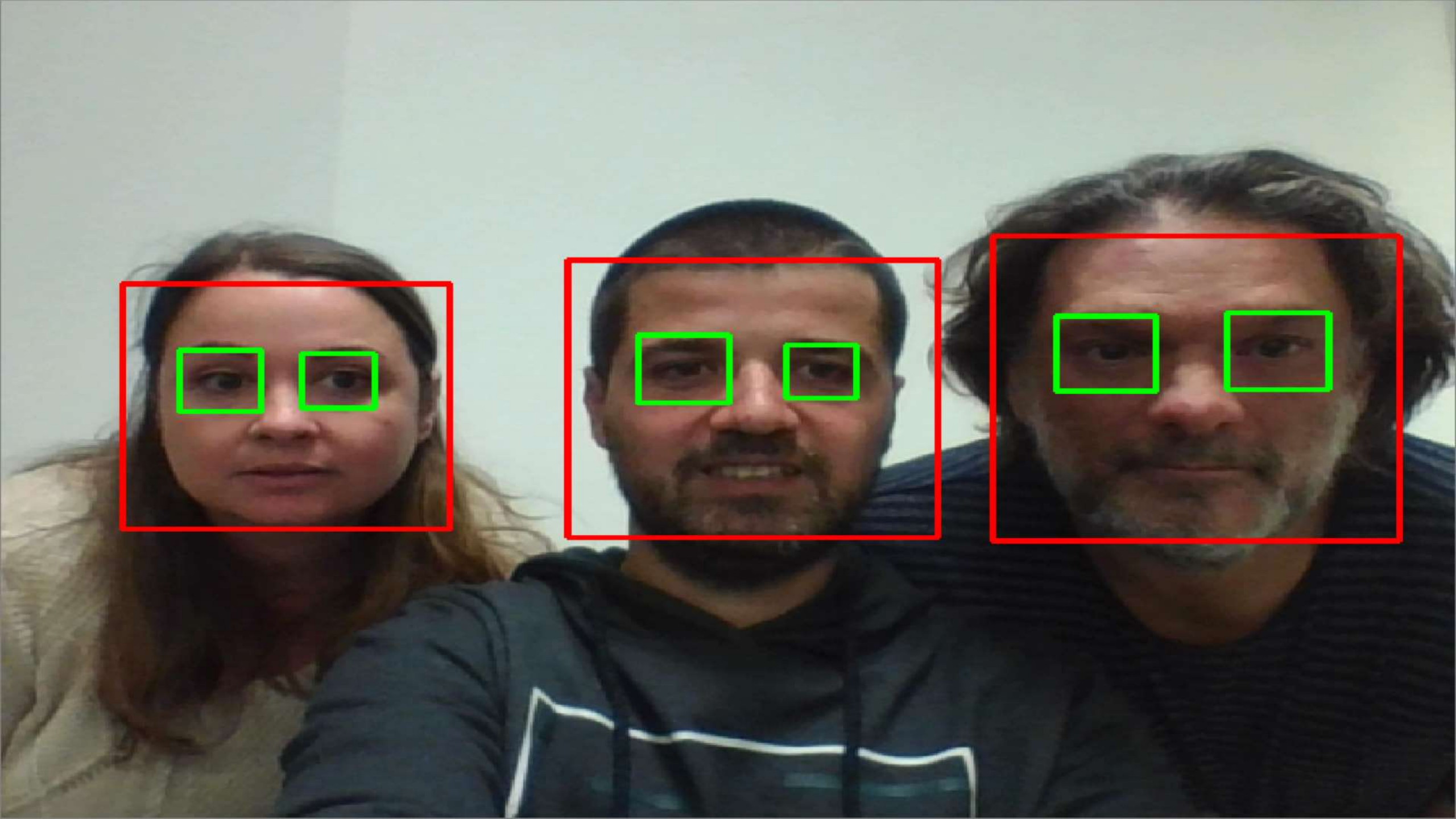
    # loop over the eyes and draw
    for (ex,ey,ew,eh) in eyes:
        cv2.rectangle(frame, pt1 = (fx + ex, fy + ey), ...)

# Display the output
cv2.imshow(windowName, frame)

# The reference to the video is released
video.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```





Hands-On Labs



obj_tracking.py

```
# Import the necessary packages
import argparse
import numpy as np
import time
import cv2

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-v", "--video", required = False,
                help = "path to where the video resides (optional)")
ap.add_argument("-t", "--threshold", required = False,
                action='store_true', help = "show threshold images (optional)")
ap.add_argument("-m", "--mirror", required = False, action='store_true',
                help = "enable mirror mode (optional)")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode (optional)")
args = vars(ap.parse_args())

# Configure windows
windowName = "Object Tracking"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                          cv2.WINDOW_FULLSCREEN)
```

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obj_tracking.py

```
# The object that will be tracking is a "yellow" object.
colorLower = (20, 100, 100)
colorUpper = (30, 255, 255)

# If --video is not supplied we will read video from the webcam.
# Otherwise, open the video file pointed by the --video argument
if (args["video"]):
    video = cv2.VideoCapture(args["video"])
else:
    video = cv2.VideoCapture(0)

# Display the video or webcam to our screen
while True:
    (grabbed, frame) = video.read()

    # Detect if video finished
    if (args["video"] and not grabbed): break

    # Mirror effect on webcam: Flip on Y axis
    if (not args["video"] and args["mirror"]):
        frame = cv2.flip(frame,1)

    # Find shades of the yellow in the frame using the cv2.inRange
    # The result is a thresholded image with pixels falling within
    # the upper and lower set to white and pixels that do not fall
    # into this range se as black
    threshold = cv2.inRange(frame, colorLower, colorUpper)
    threshold = cv2.GaussianBlur(threshold, (3,3), 0)
```

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obj_tracking.py

```
# Display threshold images
if (args["threshold"]): cv2.imshow("threshold", threshold)

# Now that we have the thresholded image, we need to find the
# largest contour in the image
(contours, h) = cv2.findContours(threshold.copy(),
                                mode = cv2.RETR_EXTERNAL, method = cv2.CHAIN_APPROX_SIMPLE)
if (len(contours) > 0) :
    contour = sorted(contours, key = cv2.contourArea,
                    reverse = True)[0]

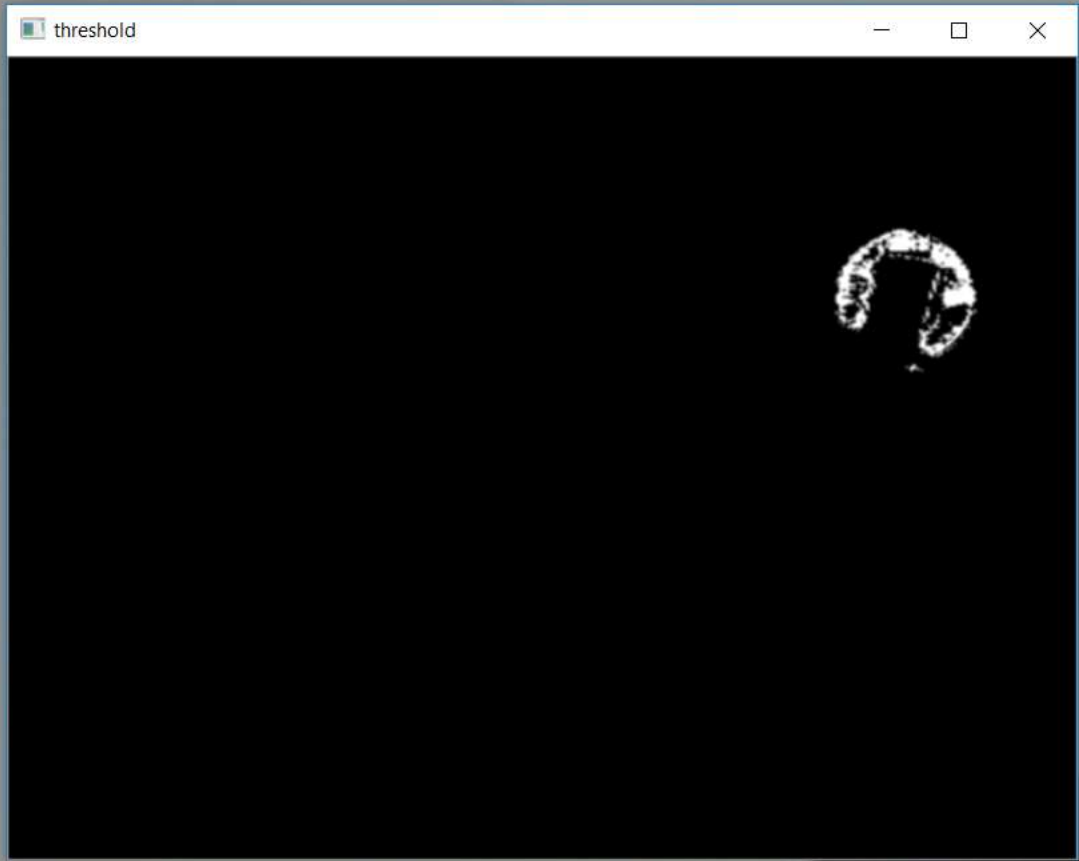
# To draw the contours, cv2.drawContours function is used.
rect = np.int32(cv2.boxPoints(cv2.minAreaRect(contour)))
cv2.drawContours(frame, contours = [rect],
                contourIdx = -1, color = (0, 255, 0), thickness = 2)

cv2.imshow(windowName, frame)

# Wait for a key press to finish program
key = cv2.waitKey(1)
if (key in [ord("q"), 27] or ...

# The reference to the video is released
video.release()

# Any open window created by OpenCV are closed
cv2.destroyAllWindows()
```







"HANG ZEN"



QUIKSILVER



Hands-On Labs



multi_object_tracking.py

```
# import the necessary packages
import argparse
import cv2

# construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-v", "--video", required = False,
                help = "path to where the video resides (optional)")
ap.add_argument("-m", "--mirror", required = False,
                action='store_true', help = "enable mirror mode (optional)")
ap.add_argument("-f", "--full", required = False, action='store_true',
                help = "use full screen mode (optional)")
ap.add_argument("-t", "--tracker", type=str, required = False,
                default="csrt", help="OpenCV object tracker type (optional)")
args = vars(ap.parse_args())

# Configure windows
windowName = "Multi Tracking"
if (args["full"]):
    cv2.namedWindow(windowName, cv2.WND_PROP_FULLSCREEN)
    cv2.setWindowProperty(windowName, cv2.WND_PROP_FULLSCREEN,
                           cv2.WINDOW_FULLSCREEN)
```

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multi_object_tracking.py

```
# Initialize a dictionary that maps strings to their corresponding
# OpenCV object tracker implementations
# I recommend the following three algorithms:
# KCF: Fast and accurate
# CSRT: More accurate than KCF but slower
# MOSSE: Extremely fast but not as accurate as either KCF or CSRT
OPENCV_OBJECT_TRACKERS = {
    "csrt": cv2.TrackerCSRT_create,
    "kcf": cv2.TrackerKCF_create,
    "boosting": cv2.TrackerBoosting_create,
    "mil": cv2.TrackerMIL_create,
    "tld": cv2.TrackerTLD_create,
    "medianflow": cv2.TrackerMedianFlow_create,
    "mosse": cv2.TrackerMOSSE_create
}

# Initialize OpenCV's special multi-object tracker
# The class allows us to:
# Add new object trackers to the MultiTracker
# Update all object trackers inside the MultiTracker
trackers = cv2.MultiTracker_create()

# If --video is not supplied we will read video from the webcam.
if (args["video"]):
    video = cv2.VideoCapture(args["video"])
else:
    video = cv2.VideoCapture(0)
```

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multi_object_tracking.py

```
# loop over frames from the video stream
while True:
    # grab the current frame, then handle if we are using a
    # VideoStream or VideoCapture object
    (grabbed, frame) = video.read()

    # Detect if video finished
    if (args["video"] and not grabbed): break

    # Mirror effect on webcam: Flip on Y axis
    if (not args["video"] and args["mirror"]):
        frame = cv2.flip(frame,1)

    # grab the updated bounding box coordinates (if any) for each
    # object that is being tracked
    # The update method will locate the object's new position and
    # return a success boolean
    # and the bounding box of the object.
    (success, boxes) = trackers.update(frame)

    # loop over the bounding boxes and draw then on the frame
    for box in boxes:
        (x, y, w, h) = [int(v) for v in box]
        cv2.rectangle(frame, (x, y), (x + w, y + h), (0, 255, 0), 2)

    # show the output frame
    cv2.imshow(windowName, frame)
```

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multi_object_tracking.py

```
key = cv2.waitKey(1)

# if the 's' key is selected, we are going to "select" a
# bounding box to track
if key == ord("s"):

    # select the bounding box of the object we want to track (make
    # sure you press ENTER or SPACE after selecting the ROI)
    box = cv2.selectROI(windowName, frame, fromCenter=False,
                        showCrosshair=True)

    # create a new object tracker for the bounding box and add it
    # to our multi-object tracker
    tracker = OPENCV_OBJECT_TRACKERS[args["tracker"]]()
    trackers.add(tracker, frame, box)

# if the `q` key was pressed, break from the loop
elif (key in [ord("q"), 27] or ...):
    break

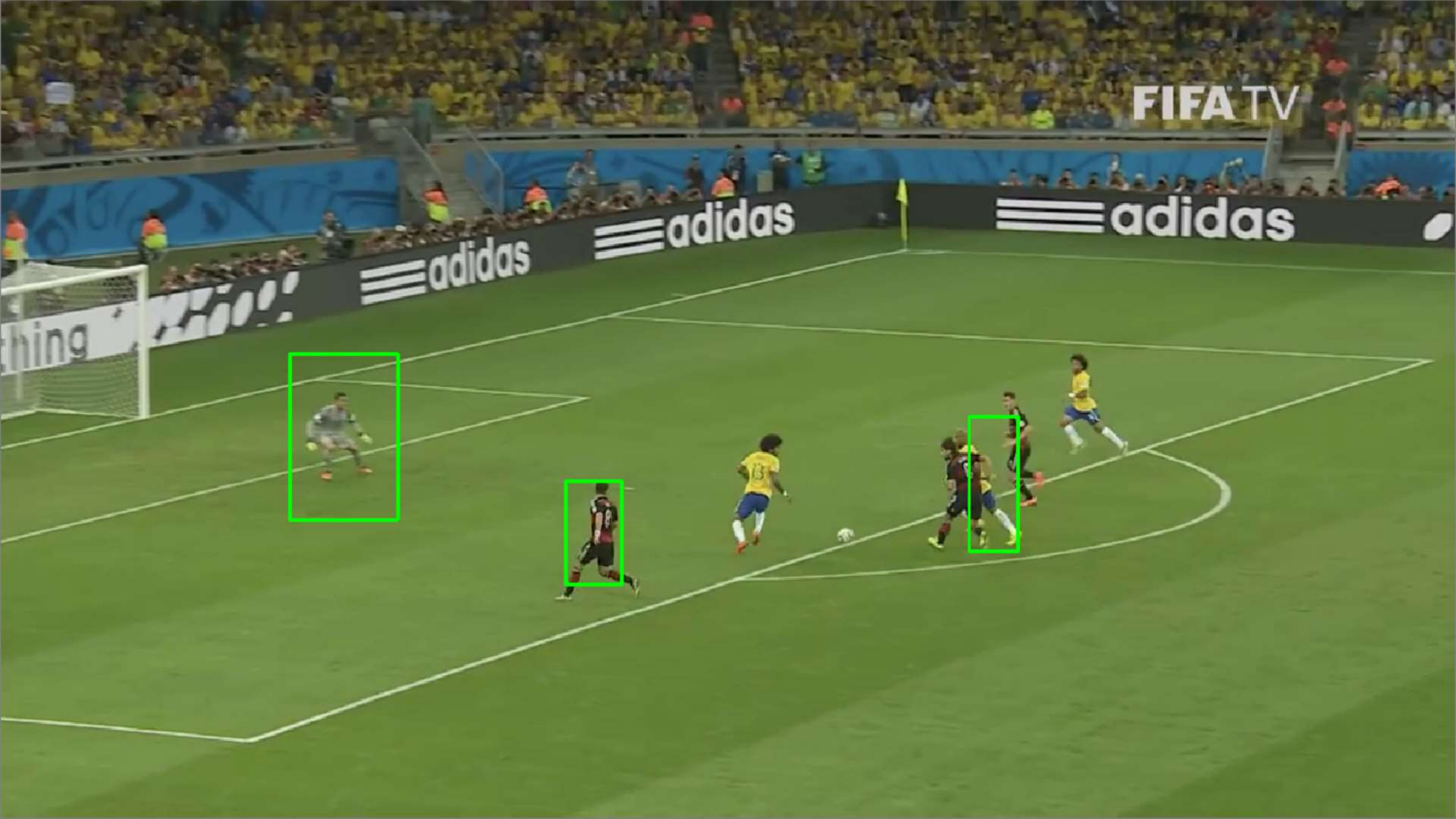
video.release()

# close all windows
cv2.destroyAllWindows()
```

FIFA TV

adidas

adidas



01. Usain Bolt



MisterFilOfficial

100m Men

WR	9.69	CR	9.80
----	------	----	------

6.6

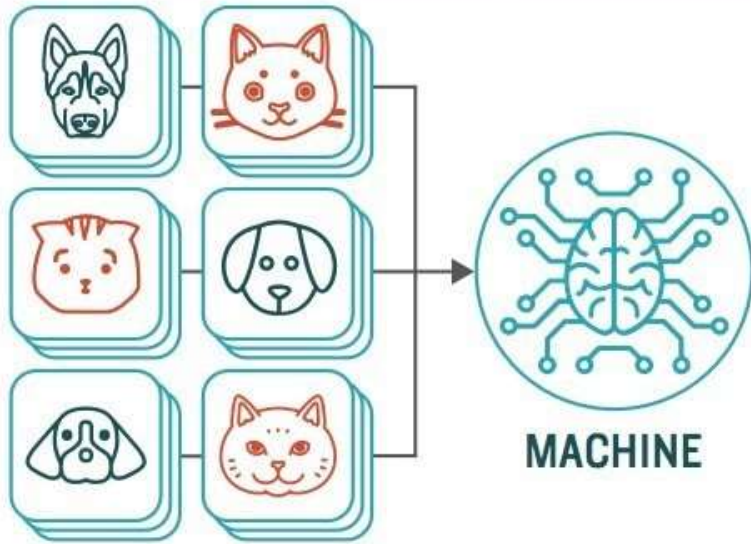
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How **Unsupervised** Machine Learning Works

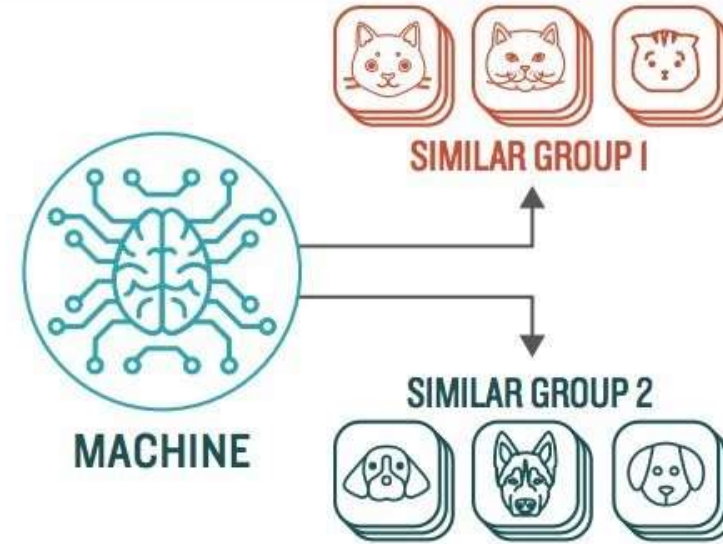
STEP 1

Provide the machine learning algorithm uncategorized, unlabeled input data to see what patterns it finds

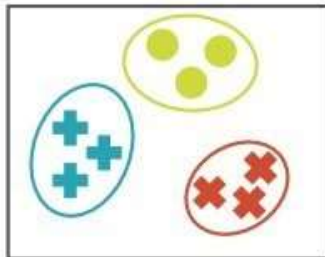


STEP 2

Observe and learn from the patterns the machine identifies



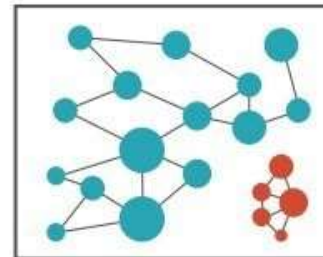
TYPES OF PROBLEMS TO WHICH IT'S SUITED



CLUSTERING

Identifying similarities in groups

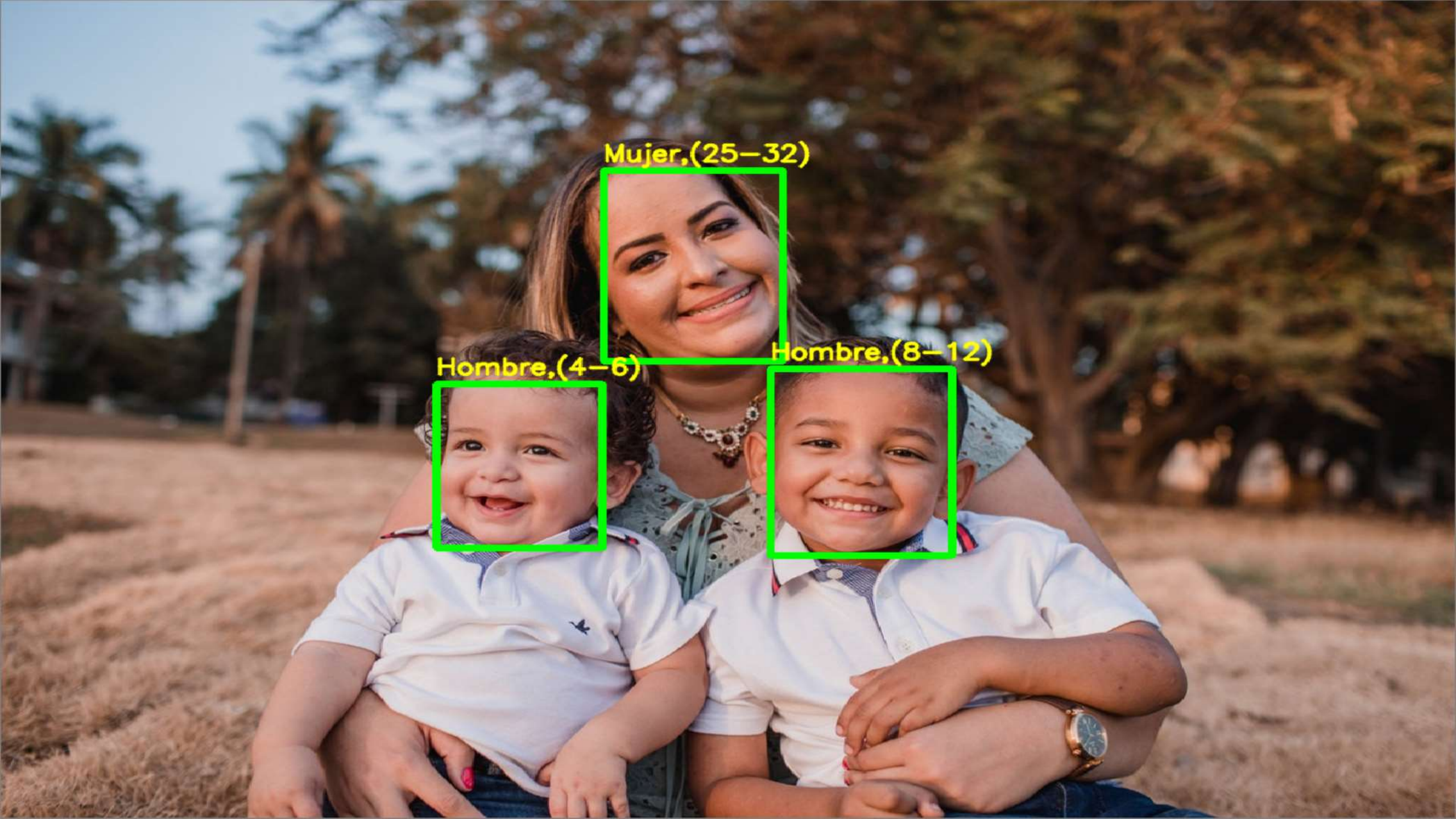
For Example: Are there patterns in the data to indicate certain patients will respond better to this treatment than others?



ANOMALY DETECTION

Identifying abnormalities in data

For Example: Is a hacker intruding in our network?



Mujer, (25-32)



Hombre, (4-6)



Hombre, (8-12)



Hombre, (25–32)



Mujer, (15–20)



Mujer, (48-53)



Hombre, (48-53)



Mujer, (15-20)



Hombre, (25-32)



Hombre, (25-32)

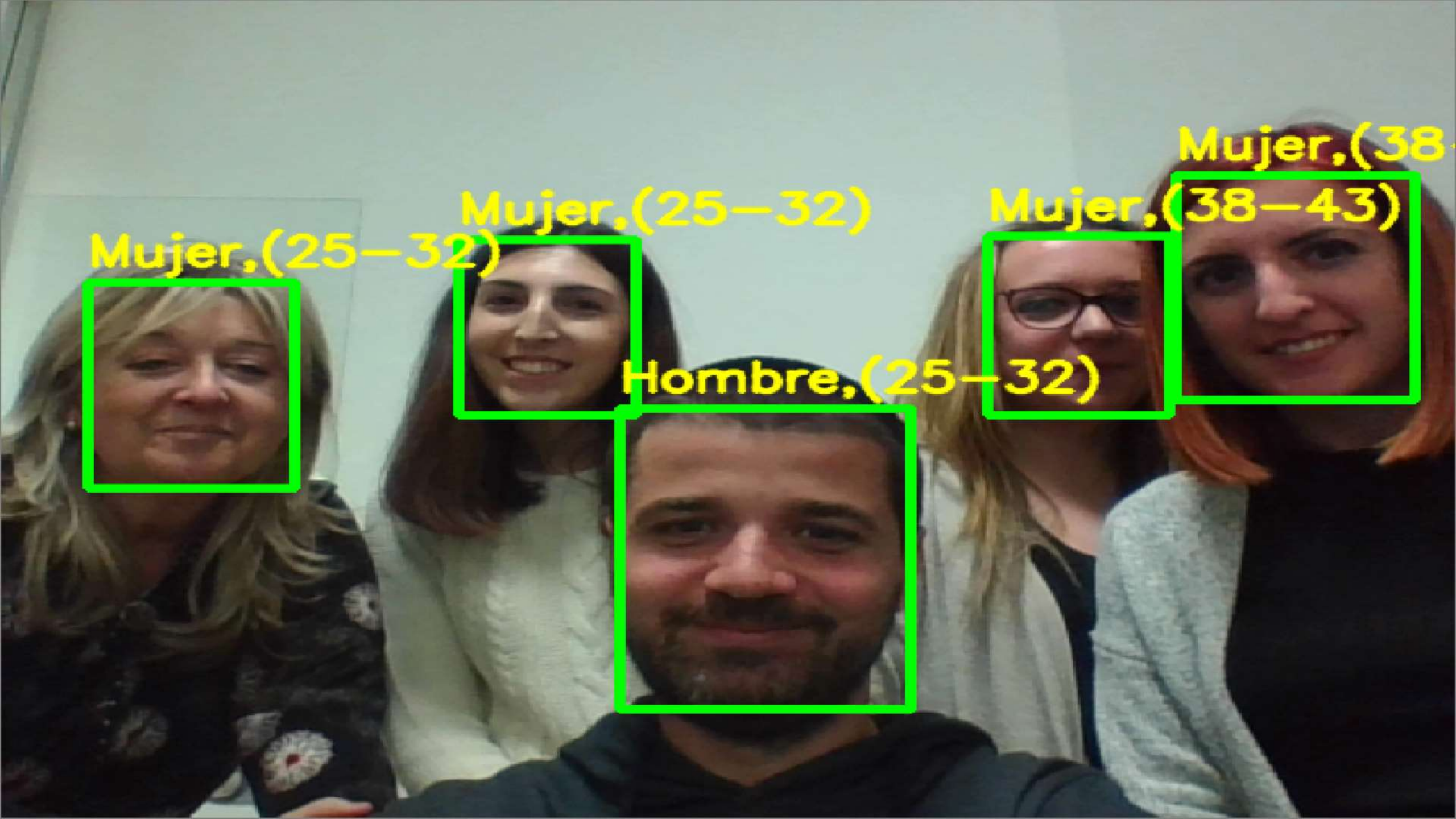


Hombre, (25-32)



Hombre, (





Mujer, (25-32)

Mujer, (25-32)

Hombre, (25-32)

Mujer, (38-43)

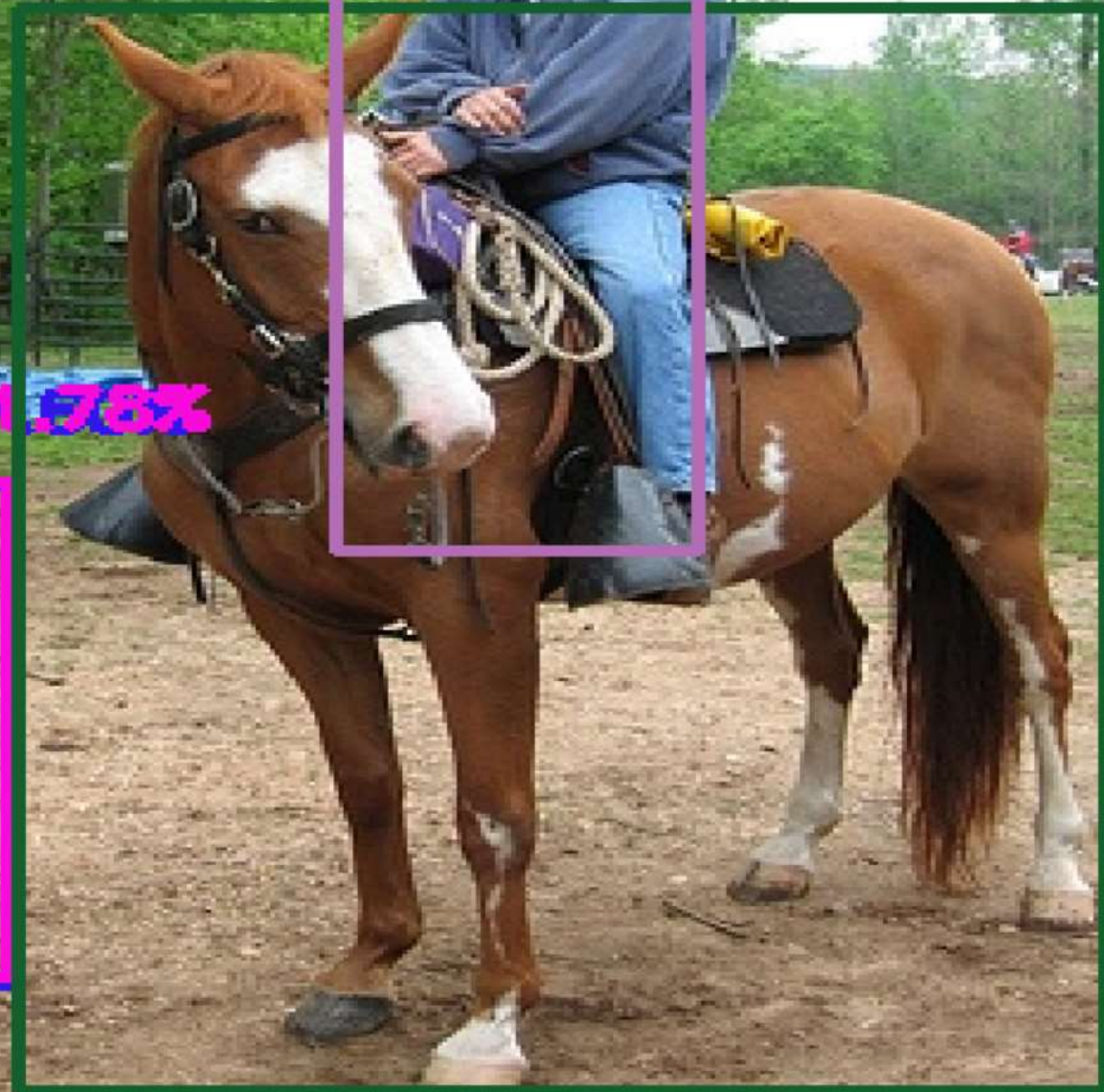
Mujer, (38-43)

person: 88.44%

horse: 99.91%

car: 99.43%

dog: 51.78%



car: 97.42%



car: 99.93%



Cloud AI solutions



Cloud Job Discovery



Contact Center



Recommendation Engine

ML professional services & partners



ASL



Professional services organization



Partner ecosystem

Cloud AI building blocks

Sight



Cloud Video Intelligence



Cloud Vision



AutoML Vision

Language



Cloud Natural Language



AutoML Natural Language



Cloud Translation



AutoML Translation

Conversation



Cloud Speech-to-Text



Dialogflow Enterprise



Cloud Text-to-Speech

Cloud AI platform



Cloud ML Engine



Cloud Dataflow



Cloud Dataproc

ML libraries



Tensorflow



Spark



beam



R



Torch



Spark MLlib



learn

Kaggle / Datasets



Kaggle



Datasets



Cloud Vision

Extrae información valiosa a partir de imágenes con nuestros potentes modelos de API ya preparados o prepara modelos de visión personalizados de forma sencilla con AutoML Vision^{BETA}

 PRUÉBALO GRATIS

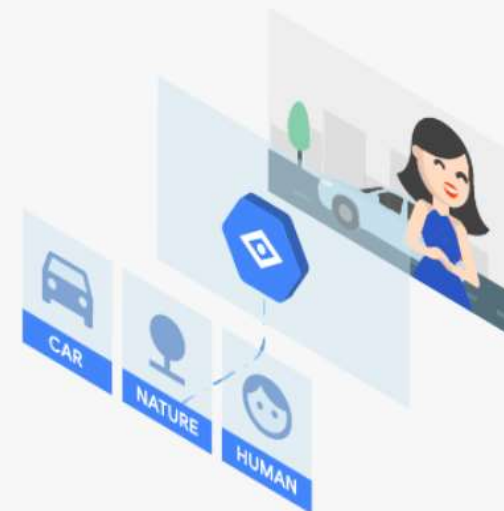
Consulta la [documentación](#) de este producto.

Potente análisis de imágenes

La API Cloud Vision utiliza modelos ya preparados y permite crear modelos personalizados y flexibles que se adaptan a cada caso práctico a través de AutoML Vision.

La **API Cloud Vision** permite que los desarrolladores comprendan el contenido de una imagen mediante el encapsulado de potentes modelos de aprendizaje automático en una API REST fácil de usar. Esta API clasifica las imágenes rápidamente en miles de categorías (por ejemplo, "barco de vela"), detecta objetos y caras determinados dentro de dichas imágenes y es capaz de leer las palabras impresas que contengan. De este modo, puedes crear metadatos en tu catálogo de imágenes, moderar el contenido ofensivo o habilitar nuevas situaciones de marketing mediante el análisis de opinión en imágenes.

Gracias a la [versión beta de AutoML Vision](#), los desarrolladores con una experiencia limitada en el ámbito del aprendizaje automático pueden preparar modelos personalizados de alta calidad. Una vez subidas y etiquetadas las imágenes, AutoML Vision prepara un modelo que puede escalarse según sea necesario para adaptarse a necesidades específicas. AutoML Vision ahorra tiempo a la hora de crear modelos que, además



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```
> pip install google-cloud-vision
Collecting google-cloud-vision
  Downloading
    https://files.pythonhosted.org/packages/f2/bf/112a0707a425961516693ac526725bc3f51db44fc3d02998da3ee2b82ef1/google_cloud_vision-0.36.0-py2.py3-none-any.whl (383kB)
    |████████████████████████████████████████████████████████████████████████████████| 389kB 1.6MB/s
Collecting google-api-core[grpc]<2.0.0dev,>=1.6.0 (from google-cloud-vision)
  Downloading
    https://files.pythonhosted.org/packages/bf/e4/b22222bb714947eb459dc91ebf95131812126a0b29d62e444be3f76dad64/google_api_core-1.9.0-py2.py3-none-any.whl (65kB)
    |████████████████████████████████████████████████████████████████████████████████| 71kB 2.3MB/s
Collecting google-auth<2.0dev,>=0.4.0 (from google-api-core[grpc]<2.0.0dev,>=1.6.0->google-cloud-vision)
...
Successfully installed cachetools-3.1.0 certifi-2019.3.9 chardet-3.0.4 google-api-core-1.9.0 google-auth-1.6.3 google-cloud-vision-0.36.0 googleapis-common-protos-1.5.9 grpcio-1.20.1 idna-2.8 protobuf-3.7.1 pyasn1-0.4.5 pyasn1-modules-0.2.5 pytz-2019.1 requests-2.21.0 rsa-4.0 six-1.12.0 urllib3-1.24.2
```

<https://pypi.org/project/google-cloud-vision/>

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```
> pip list
```

Package	Version
-----	-----
cachetools	3.1.0
certifi	2019.3.9
chardet	3.0.4
google-api-core	1.9.0
google-auth	1.6.3
google-cloud-vision	0.36.0
googleapis-common-protos	1.5.9
grpcio	1.20.1
idna	2.8
numpy	1.16.3
opencv-contrib-python	4.1.0.25
pip	19.1
protobuf	3.7.1
pyasn1	0.4.5
pyasn1-modules	0.2.5
pytz	2019.1
requests	2.21.0
...	

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logo_detection.py

```
# Import the necessary packages
import io
import os
from google.cloud import vision
from google.cloud.vision import types
import argparse

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
args = vars(ap.parse_args())

# Authenticate API requests
os.environ['GOOGLE_APPLICATION_CREDENTIALS'] = "credentials.json"

# The name of the image file to annotate
filename = os.path.join(os.path.dirname(__file__), args["image"])

# Loads the image into memory
with io.open(filename, 'rb') as file:
    content = file.read()
```

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Google Cloud Platform



logo_detection.py

```
# Instantiates a client
client = vision.ImageAnnotatorClient()
image = types.Image(content = content)

# Performs object localization on the image file
response = client.logo_detection(image)

# Process the response
logos = response.logo_annotations

# Print JSON response
print(logos)

print(f'Number of logos found: {len(logos)}')
print("-----")
for logo in logos:
    print(f'Logo: {logo.description}')
    print(f'Score: {logo.score}')
    print("-----")
```

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Google Cloud Platform



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logo_detection.py

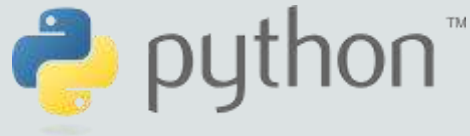
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Google

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Google Cloud Platform



logo_detection.py

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Number of logos found: 1

Logo: google

Score: 0.9927250146865845

```
{
  mid: "/m/045c7b"
  description: "google"
  score: 0.9927250146865845
  bounding_poly {
    vertices {
    }
    vertices {
      x: 759
    }
    vertices {
      x: 759
      y: 439
    }
    vertices {
      y: 439
    }
  }
}
```

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logo_detection.py

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logo_detection.py

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Number of logos found: 1

Logo: mcdonalds

Score: 0.9921749830245972

```
{
  mid: "/m/07gyp7"
  description: "mcdonalds"
  score: 0.9921749830245972
  bounding_poly {
    vertices {
    }
    vertices {
      x: 923
    }
    vertices {
      x: 923
      y: 600
    }
    vertices {
      y: 600
    }
  }
}
```

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Google Cloud Platform



object_detection.py

```
# Import the necessary packages
import io
import os
from google.cloud import vision
from google.cloud.vision import types
import argparse

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
args = vars(ap.parse_args())

# Authenticate API requests
os.environ['GOOGLE_APPLICATION_CREDENTIALS'] = "credentials.json"

# The name of the image file to annotate
filename = os.path.join(os.path.dirname(__file__), args["image"])

# Loads the image into memory
with io.open(filename, 'rb') as file:
    content = file.read()
```

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object_detection.py

```
# Instantiates a client
client = vision.ImageAnnotatorClient()
image = types.Image(content = content)

# Performs object localization on the image file
response = client.object_localization(image)

# Process the response
objects = response.localized_object_annotations

# Print JSON response
print(objects)

print(f'Number of objects found: {len(objects)}')
for obj in objects:
    print(f'{obj.name} (confidence: {obj.score})')
    print('Normalized bounding polygon vertices: ')
    for vertex in obj.bounding_poly.normalized_vertices:
        print(f' - ({vertex.x}, {vertex.y})')
```

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```
Number of objects found: 5
Bird (confidence: 0.9233673810958862)
Duck (confidence: 0.8315161466598511)
Animal (confidence: 0.7112061977386475)
Wheel (confidence: 0.5616657733917236)
Toy (confidence: 0.5473584532737732)
```

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text_detection.py

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```
# Import the necessary packages
import io
import os
from google.cloud import vision
from google.cloud.vision import types
import argparse

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
args = vars(ap.parse_args())

# Authenticate API requests
os.environ['GOOGLE_APPLICATION_CREDENTIALS'] = "credentials.json"

# The name of the image file to annotate
filename = os.path.join(os.path.dirname(__file__), args["image"])

# Loads the image into memory
with io.open(filename, 'rb') as file:
    content = file.read()
```

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text_detection.py

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```
# Instantiates a client
client = vision.ImageAnnotatorClient()
image = types.Image(content = content)

# Performs object localization on the image file
response = client.text_detection(image)

# Process the response
texts = response.text_annotations

# Print JSON response
print(texts)

print(f'Number of text fragments found: {len(texts)}')
for text in texts:
    print("-----")
    print(f'{text.description}')
    print("-----")
```

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text_detection.py

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Number of text fragments found: 3

3685 HDP

3685

HDP

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face_detection.py

```
# Import the necessary packages
import io
import os
from google.cloud import vision
from google.cloud.vision import types
import argparse

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
args = vars(ap.parse_args())

# Authenticate API requests
os.environ['GOOGLE_APPLICATION_CREDENTIALS'] = "credentials.json"

# The name of the image file to annotate
filename = os.path.join(os.path.dirname(__file__), args["image"])

# Loads the image into memory
with io.open(filename, 'rb') as file:
    content = file.read()
```


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face_detection.py

```
# Instantiates a client
client = vision.ImageAnnotatorClient()
image = types.Image(content = content)

# Performs object localization on the image file
response = client.face_detection(image)

# Process the response
faces = response.face_annotations

# Print JSON response
print(faces)

print(f'Number of faces found: {len(faces)}')
for face in faces:
    print("-----")
    print(f"Confidence: {face.detection_confidence}")
    print(f"Alegre: {face.joy_likelihood}")
    print(f"Triste: {face.sorrow_likelihood}")
    print(f"Enfadado: {face.anger_likelihood}")
    print(f"Sorprendido: {face.surprise_likelihood}")
    print(f"Borroso: {face.blurred_likelihood}")
    print(f"Con sombrero: {face.headwear_likelihood}")
    print("-----")
```

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Google Cloud Platform

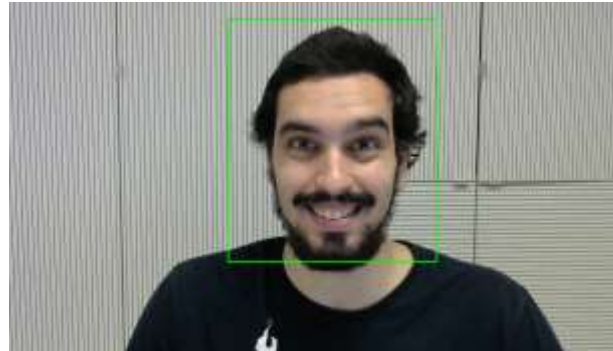


face_detection.py

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Confidence: 0.9987232685089111
Alegre: 1
Triste: 2
Enfadado: 1
Sorprendido: 1
Borroso: 1
Con sombrero: 1



Confidence: 0.9991716146469116
Alegre: 5
Triste: 1
Enfadado: 1
Sorprendido: 1
Borroso: 1
Con sombrero: 1



Confidence: 0.999671459197998
Alegre: 1
Triste: 1
Enfadado: 1
Sorprendido: 5
Borroso: 1
Con sombrero: 1

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landmark_detection.py

```
# Import the necessary packages
import io
import os
from google.cloud import vision
from google.cloud.vision import types
import argparse

# Construct the argument parser and parse the arguments
ap = argparse.ArgumentParser()
ap.add_argument("-i", "--image", required = True,
                help = "path to where the image file resides")
args = vars(ap.parse_args())

# Authenticate API requests
os.environ['GOOGLE_APPLICATION_CREDENTIALS'] = "credentials.json"

# The name of the image file to annotate
filename = os.path.join(os.path.dirname(__file__), args["image"])

# Loads the image into memory
with io.open(filename, 'rb') as file:
    content = file.read()
```

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landmark_detection.py

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```
# Instantiates a client
client = vision.ImageAnnotatorClient()
image = types.Image(content = content)

# Performs object localization on the image file
response = client.landmark_detection(image)

# Process the response
landmarks = response.landmark_annotations

# Print JSON response
print(landmarks)

print(f'Number of landmarks found: {len(landmarks)}')
for landmark in landmarks:
    print("-----")
    print(f"Description: {landmark.description}")
    print(f"Score: {landmark.score}")
    print("-----")
```

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Description: Plaza de Cibeles

Score: 0.9911772012710571

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Google Cloud Platform



Description: Puerta del Sol, Post Office

Score: 0.5609591007232666



¡Muchas gracias!

jordi.arino@pue.es
[@jordiAS2K](https://twitter.com/jordiAS2K)



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